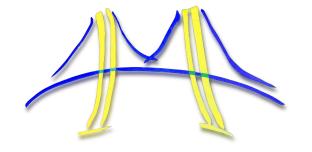


# Minimizing Communication in Linear Algebra



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## Summary

- New communication lower bounds for (nearly) all dense or sparse, sequential or parallel, direct linear algebra problems
- New algorithms that attain lower bounds (sequential and parallel)
- Measured and modeled speedups, not just asymptotics
- Open problems in dense and sparse linear algebra

#### **Motivation**

## "Communication" means

## **Communication-Avoiding LU (CALU)**

- Factor panel once with "Tall Skinny LU" (like a block reduction) to choose pivots
- Swap pivot rows to top and factor *again* without pivoting  $O(n^2)$  extra flops
- $\bullet$  Measured speedup of parallel TSLU: up to  $5.58\times$  on Cray XT4
- Measured speedup of parallel CALU (size  $10^4 \times 10^4$ ):  $1.31 \times$  on Cray XT4
- See [DGX08] for details, models, and more performance results

**Current Work** 

- Parallel: Data movement between processors
- Sequential: Data movement between levels of memory hierarchy
- # words (inverse bandwidth) and # messages (latency)

# **Communication matters because:**

- Much slower than flops, and getting *exponentially slower* over time
- Moving data much more *energy-intensive* than computing on it

## Lower Bounds

# **Dense Matrix Multiplication**

Lower bound on: Lower bound

- # words  $\Omega\left(\# \text{ flops} / (\text{local/fast memory size})^{1/2}\right)$
- # messages  $\Omega \left( \# \text{ flops} / (\text{local/fast memory size})^{3/2} \right)$
- Results due to Hong-Kung [HK81], Irony/Tishkin/Toledo [ITT04]
- Attained by block algorithm (sequential) and Cannon's algorithm (parallel)

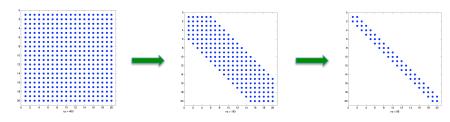
# Extensions to (nearly) all direct problems

- Theorem: same lower bounds hold for LU, Cholesky, QR, EV/SVD problems
- Sequential or parallel, dense or sparse
- -See [BDHS09] for details and proof
- Existing library routines not both bandwidth and latency optimal
- ScaLAPACK: only Cholesky is optimal; LAPACK: Cholesky bandwidth only

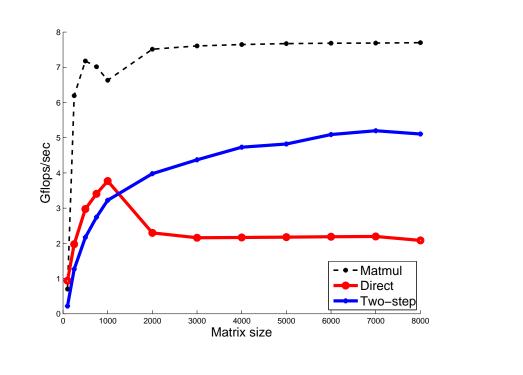
# **New Algorithms**

# **Eigenvalue/SVD Problems**

- Successive Band Reduction (SBR)
- uses two-step reduction to tridiagonal rather than one-step



pays off when only eigen/singular values are required
costs constant factor more flops when vectors are required



- First step (full to banded) can be done in optimal way
- \* using optimal QR factorization and BLAS 3 kernels
- Second step (banded to tridiagonal) is lower order term
- MKL driver routines do not yet take advantage of two-step approach
- Randomized divide-and-conquer approach
  - no reductions, uses randomized rank-revealing QR factorization
  - communication-optimal in asymptotic sense
  - -costs (larger) constant factor more flops
- $\bullet$  More flops  $\rightarrow$  pay-off in future

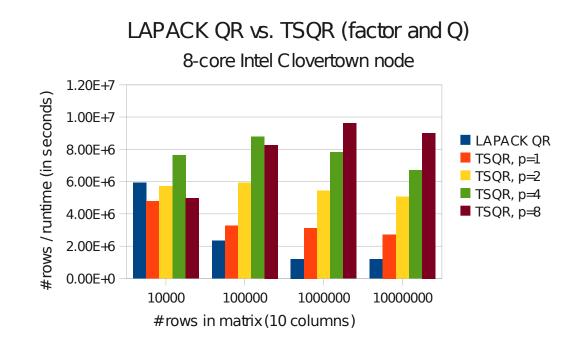
# Sparse Cholesky on 5-pt Stencil Matrix

• Gilbert ('73) proved lower bounds for sparse Cholesky factorization

# Communication-Avoiding QR (CAQR)

- Factor panel with "Tall Skinny QR" (TSQR): block reduction with QR as operator
- $\bullet$  Measured speedup of parallel TSQR: up to  $6.7\times$  on 16 processors of a Pentium III cluster
- Modeled speedup of parallel CAQR: up to  $9.7 \times$  on an IBM Power5 system
- See [DGHL08] for details, models, and more performance results
- Standalone TSQR useful for iterative methods (orthogonalize basis vectors)

# **TSQR performance results**



- Single node of 8-core Intel Clovertown (we have cluster and out-ofcore versions too)
- Includes factorization and assembling explicit Q factor
- Best number of threads for LAPACK QR (MKL and stock LAPACK): 1
- Even better measured and modeled speedups on clusters

- $\Omega(n^{3/2})$  flops,  $\Omega(n\log n)$  fill-in
- Communication lower bound is then  $\Omega\left(\max\left\{\frac{n^{3/2}}{\sqrt{M}}, n\log n\right\}\right)$
- Nested dissection attains computation/fill-in lower bound
- New variant attains communication lower bound (we think)

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