

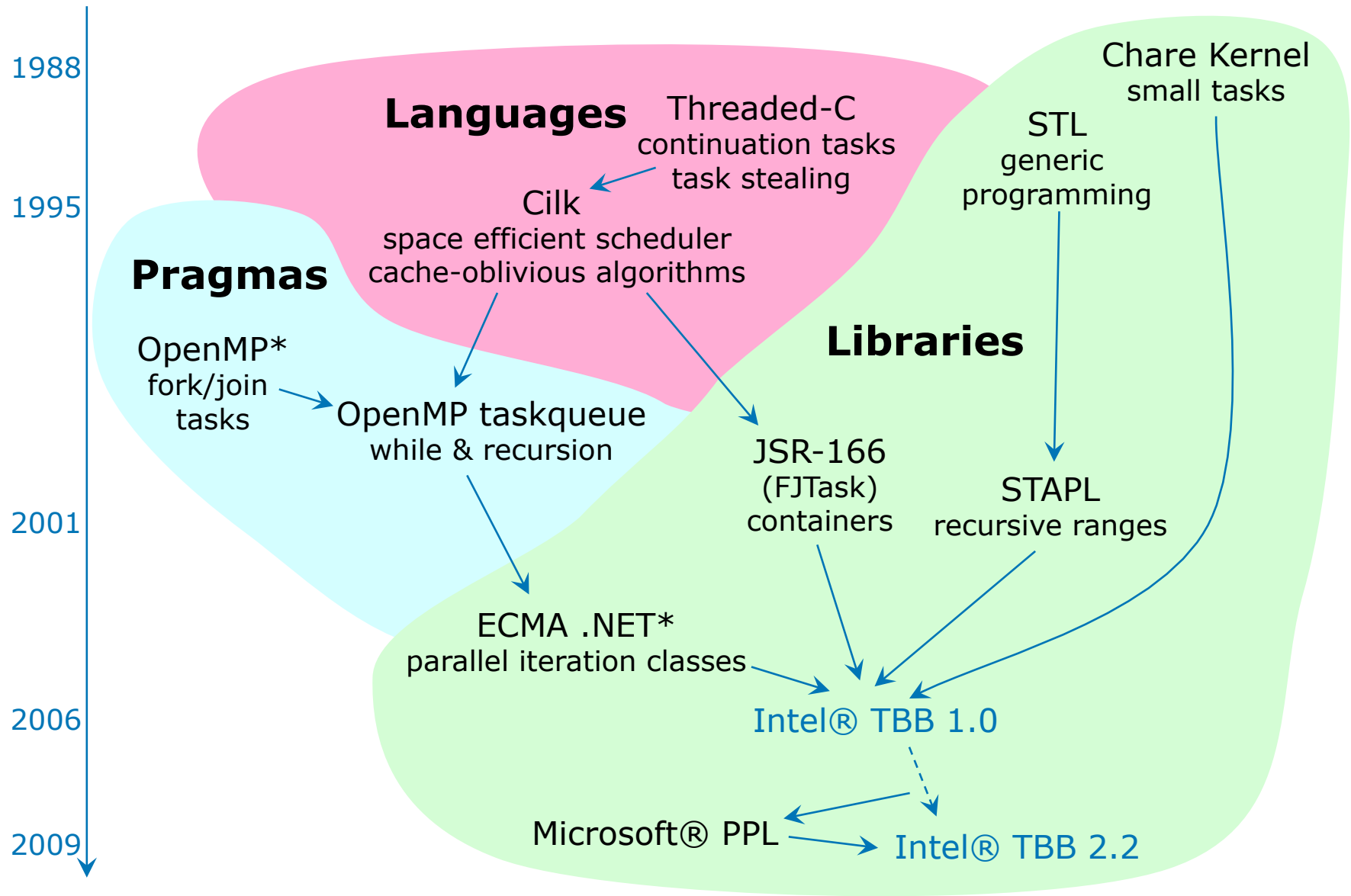


Intel® Threading Building Blocks

Michael Wrinn, Intel

ParLab Boot Camp • August 19, 2009

Family Tree



*Other names and brands may be claimed as the property of others

Key Features

Intel® Threading Building Blocks (TBB)

- ❖ It is a *template library* intended to ease parallel programming for C++ developers
 - Relies on generic programming to deliver high performance parallel algorithms with broad applicability
- ❖ It provides a *high-level abstraction* for parallelism
 - Shifts focus from workers (threads) to the work (you specify tasks patterns instead of threads)
 - Hides low level details of thread management (maps your logical tasks onto physical threads)
 - Library maps your logical tasks onto physical threads, efficiently using cache and balancing load
 - Full support for nested parallelism
- ❖ It facilitates scalable performance
 - Strives for efficient use of cache, and balances load
 - Portable across Linux*, Mac OS*, Windows*, and Solaris*
 - Emphasizes scalable data parallel programming bLoop parallelism tasks are more scalable than a fixed number of separate tasks
- ❖ Can be used in concert with other packages such as native threads and OpenMP
- ❖ Open source and licensed versions available

Check Intel® TBB online

The screenshot shows the Intel Threading Building Blocks 2.2 for Open Source website. The browser address bar shows <http://www.threadingbuildingblocks.org/>. The main banner features a yellow bird on a branch and the Intel logo. A navigation menu includes Home, Downloads, Forums, Blogs, Documentation, and About. A callout box points to the Forums and Blogs links, stating: "Active user forums, FAQs, technical blogs and TBB Developers Wiki". Another callout box points to the Unreal Technology logo, stating: "Several very important contributions were made by the OS community allowing TBB 2.1 to build and work on: Xbox* 360, Sun Solaris*, AIX*". The website content includes a welcome message, a search bar, and a list of resources such as Code Samples, FAQ, Bugs, and Make a Contribution.

Intel® Threading Building Blocks 2.2 for Open Source

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Intel® Threading Building Blocks 2.2 Commercial Version Available Now: The [commercial version](#) is available to evaluate and the [new commercially aligned release](#) is available for download now. Learn more about the great additions to TBB in 2.2 in Terry Wilmarth's and James Reinders' blogs on the Intel Software Network.

- Read [Intel's Announcement](#)
- Read Terry Wilmarth's blog [What's New in Intel® TBB 2.2?](#)
- Read James Reinders' blogs about 2.2:

Games, 2.2 has has joined

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Resources

- Code Samples
- FAQ
- Bugs
- Make a Contribution
- Commercial Version of TBB
- Intel Community for Parallelism

Limitations

- ❖ TBB is not intended for
 - I/O bound processing
 - Real-time processing
- ❖ General limitations
 - Direct use only from C++
 - Distributed memory not supported (target is desktop)
 - Requires more work than sprinkling in pragmas

Intel® TBB 2.2 Components

Generic Parallel Algorithms

parallel_for, parallel_for_each
parallel_reduce
parallel_scan
parallel_do
pipeline
parallel_sort
parallel_invoke

Task scheduler

task_group
task
task_scheduler_init
task_scheduler_observer

Synchronization Primitives

atomic, mutex, recursive_mutex
spin_mutex, spin_rw_mutex
queuing_mutex, queuing_rw_mutex
null_mutex, null_rw_mutex

Threads

tbb_thread

Concurrent Containers

concurrent_hash_map
concurrent_queue
concurrent_bounded_queue
concurrent_vector

Thread Local Storage

combinable
enumerable_thread_specific

Memory Allocation

tbb_allocator
zero_allocator
cache_aligned_allocator
scalable_allocator

Task-based Programming

- ❖ Tasks are light-weight entities at user-level
 - TBB parallel algorithms map tasks onto threads automatically
 - Task scheduler manages the thread pool
 - Scheduler is *unfair* to favor tasks that have been most recent in the cache
 - Oversubscription and undersubscription of core resources is prevented by task-stealing technique of TBB scheduler

Generic Programming

- ❖ Best known example is C++ STL
- ❖ Enables distribution of broadly-useful high-quality algorithms and data structures
- ❖ Write best possible algorithm with fewest constraints
 - Do not force particular data structure on user
 - Classic example: STL `std::sort`
- ❖ Instantiate algorithm to specific situation
 - C++ template instantiation, partial specialization, and inlining make resulting code efficient
- ❖ Standard Template Library, overall, is not *thread-safe*

Generic Programming - Example

- ❖ The compiler creates the needed versions

T must define a copy constructor
and a destructor

```
template <typename T> T max (T x, T y) {  
    if (x < y) return y;  
    return x;  
}  
  
int main() {  
    int i = max(20,5);  
    double f = max(2.5, 5.2);  
    MyClass m = max(MyClass("foo"), MyClass("bar"));  
    return 0;  
}
```

T must define operator<

TBB Parallel Algorithms

- ❖ Task scheduler powers high level parallel patterns that are pre-packaged, tested, and tuned for scalability
 - `parallel_for`: load-balanced parallel execution of loop iterations where iterations are independent
 - `parallel_reduce`: load-balanced parallel execution of independent loop iterations that perform reduction (e.g. summation of array elements)
 - `parallel_do`: load-balanced parallel execution of independent loop iterations with unknown or dynamically changing bounds (e.g. applying function to the element of linked list)
 - `parallel_scan`: template function that computes parallel prefix
 - `pipeline`: data-flow pipeline pattern
 - `parallel_sort`: parallel sort
 - `parallel_invoke`: evaluates up to 10 functions, possibly in parallel and waits for all of them to finish.

The parallel_for Template

```
template <typename Range, typename Body>  
void parallel_for(const Range& range, const Body &body);
```

- ❖ Requires definition of:
 - A range type to iterate over
 - Must define a copy constructor and a destructor
 - Defines **is_empty()**
 - Defines **is_divisible()**
 - Defines a splitting constructor, **R(R &r, split)**
 - A body type that operates on the range (or a subrange)
 - Must define a copy constructor and a destructor
 - Defines **operator()**

Body is Generic

❖ Requirements for `parallel_for` Body

<code>Body::Body(const Body&)</code>	Copy constructor
<code>Body::~~Body()</code>	Destructor
<code>void Body::operator() (Range& <i>subrange</i>) const</code>	Apply the body to <i>subrange</i> .

- ❖ `parallel_for` partitions original range into subranges, and deals out subranges to worker threads in a way that:
 - Balances load
 - Uses cache efficiently
 - Scales

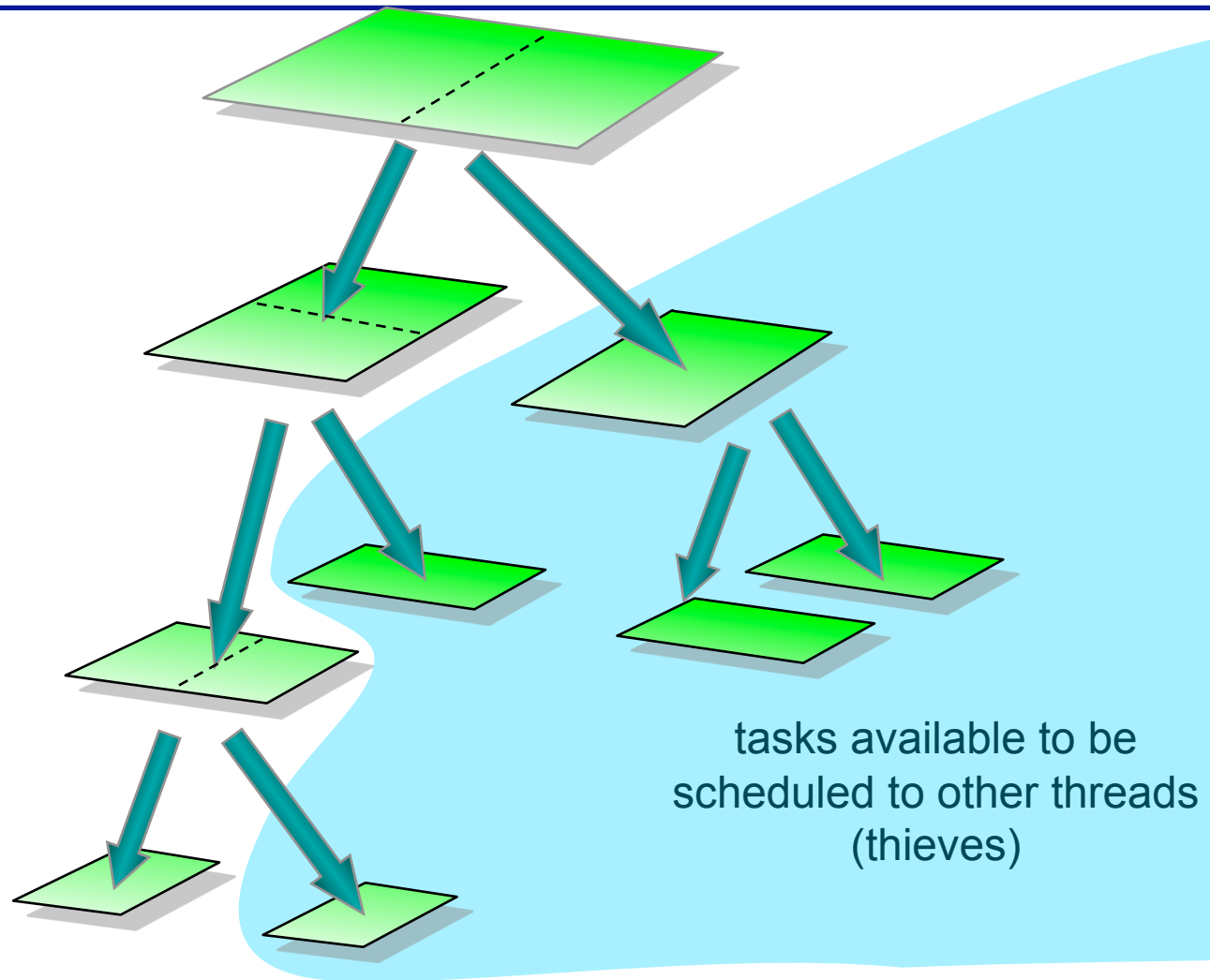
Range is Generic

❖ Requirements for `parallel_for` Range

<code>R::R (const R&)</code>	Copy constructor
<code>R::~~R()</code>	Destructor
<code>bool R::is_empty() const</code>	True if range is empty
<code>bool R::is_divisible() const</code>	True if range can be partitioned
<code>R::R (R& r, <code>split</code>)</code>	Splitting constructor; splits r into two subranges

- ❖ Library provides predefined ranges
 - `blocked_range` and `blocked_range2d`
- ❖ You can define your own ranges

How splitting works on `blocked_range2d`



Quicksort – Step 1

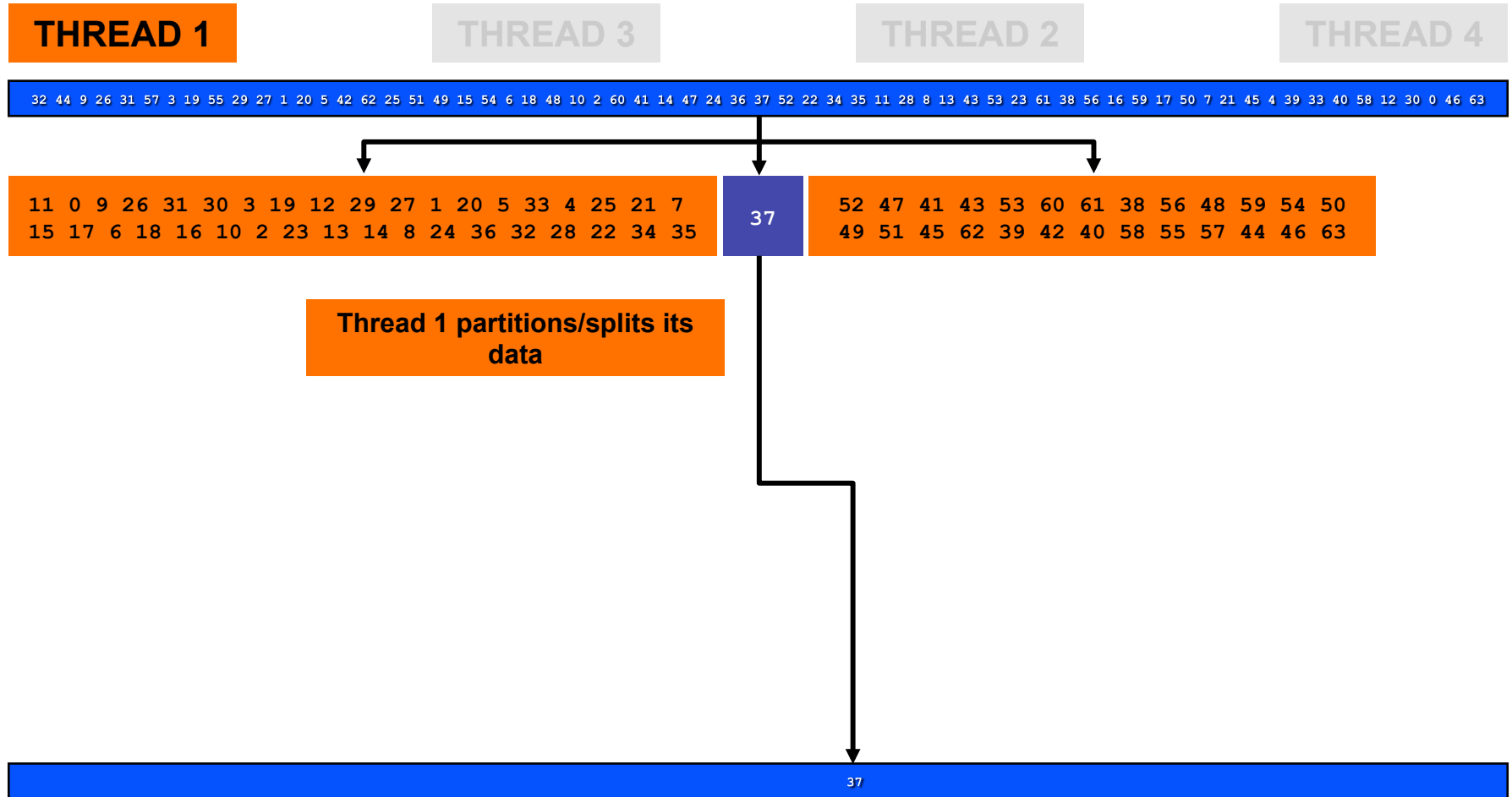
THREAD 1

32 44 9 26 31 57 3 19 55 29 27 1 20 5 42 62 25 51 49 15 54 6 18 48 10 2 60 41 14 47 24 36 37 52 22 34 35 11 28 8 13 43 53 23 61 38 56 16 59 17 50 7 21 45 4 39 33 40 58 12 30 0 46 63

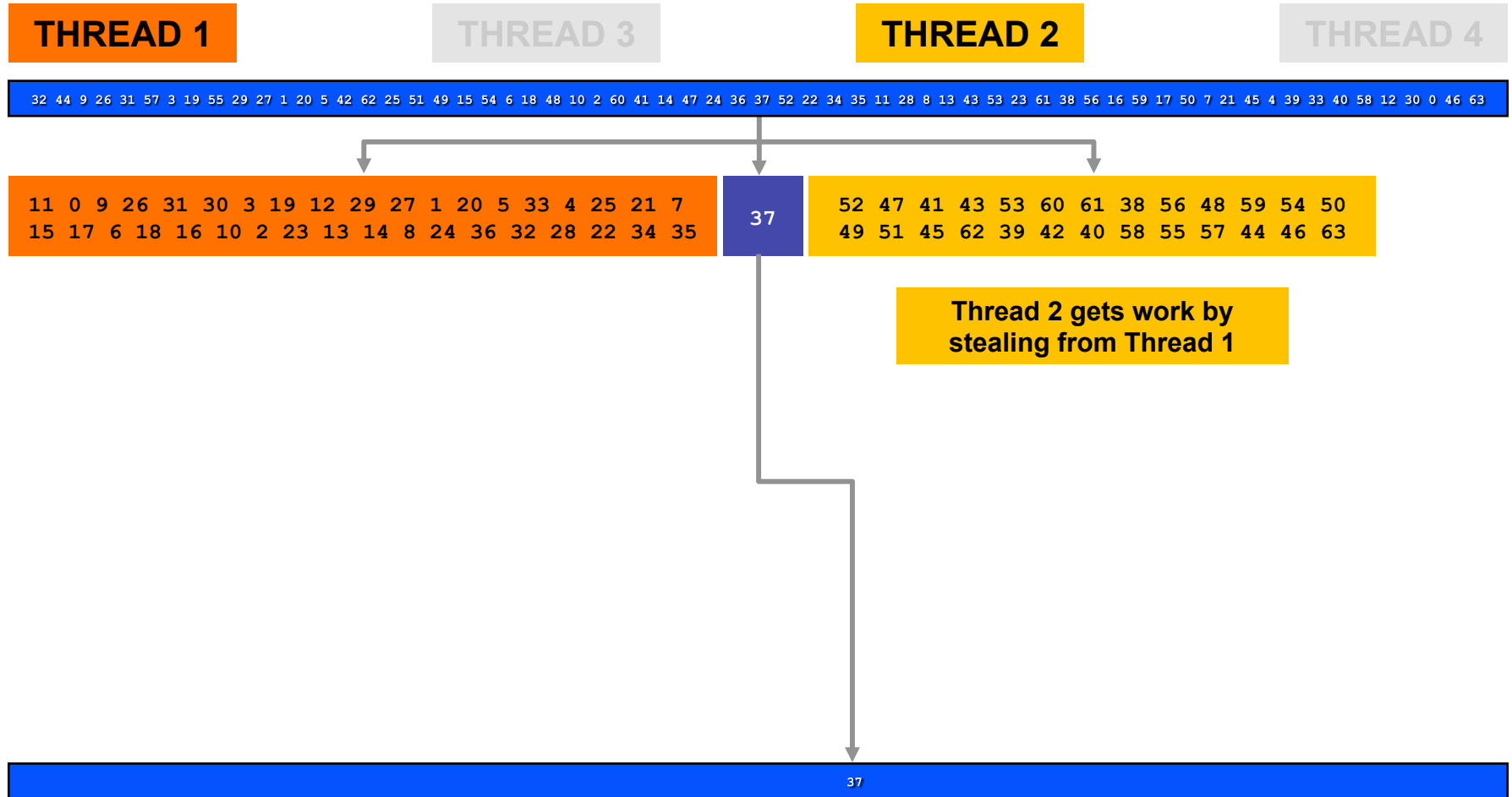
Thread 1 starts with the
initial data



Quicksort – Step 2



Quicksort – Step 2



Quicksort – Step 3

THREAD 1

THREAD 2

32 44 9 26 31 57 3 19 55 29 27 1 20 5 42 62 25 51 49 15 54 6 18 48 10 2 60 41 14 47 24 36 37 52 22 34 35 11 28 8 13 43 53 23 61 38 56 16 59 17 50 7 21 45 4 39 33 40 58 12 30 0 46 63

11 0 9 26 31 30 3 19 12 29 27 1 20 5 33 4 25 21 7
15 17 6 18 16 10 2 23 13 14 8 24 36 32 28 22 34 35

37

52 47 41 43 53 60 61 38 56 48 59 54 50
49 51 45 62 39 42 40 58 55 57 44 46 63

1 0 2 6
4 5 3

7

12 29 27 19 20 30 33 31 25 21 11 15
17 26 18 16 10 9 23 13 14 8 24 36
32 28 22 34 35

45 47 41 43
46 44 40 38
42 48 39

49

50 52 51 54 62
59 56 61 58 55
57 60 53 63

Thread 1 partitions/splits its data

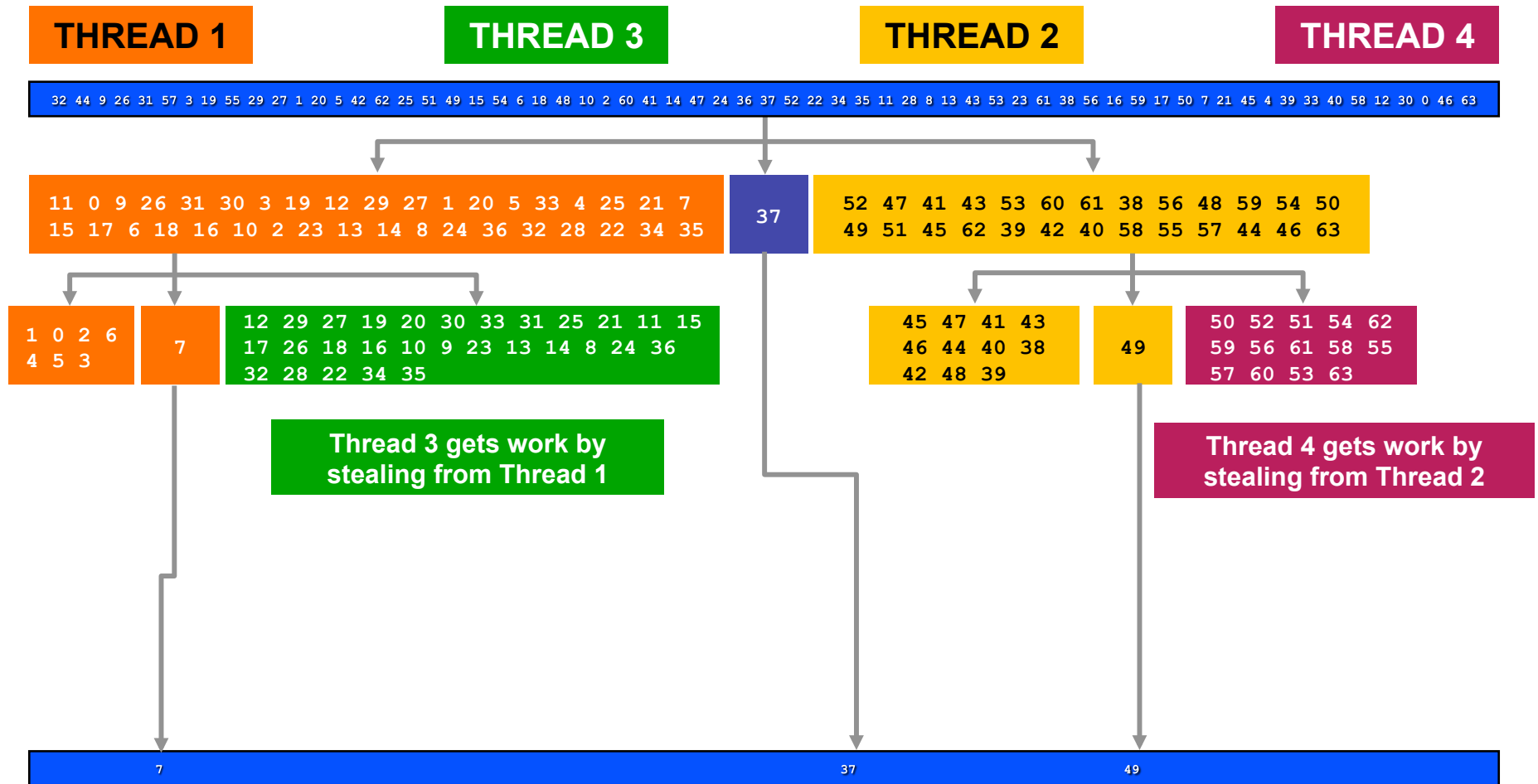
Thread 2 partitions/splits its data

7

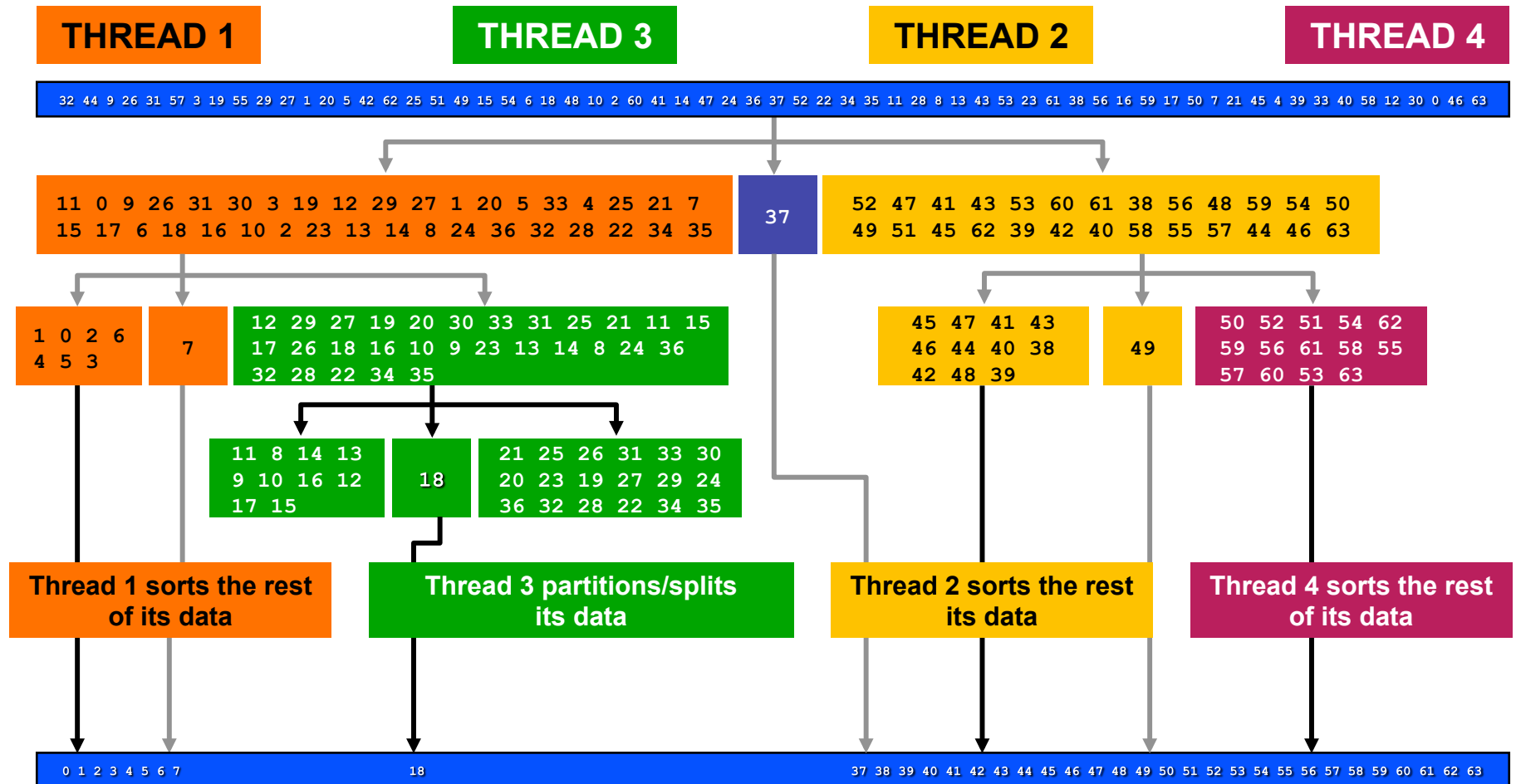
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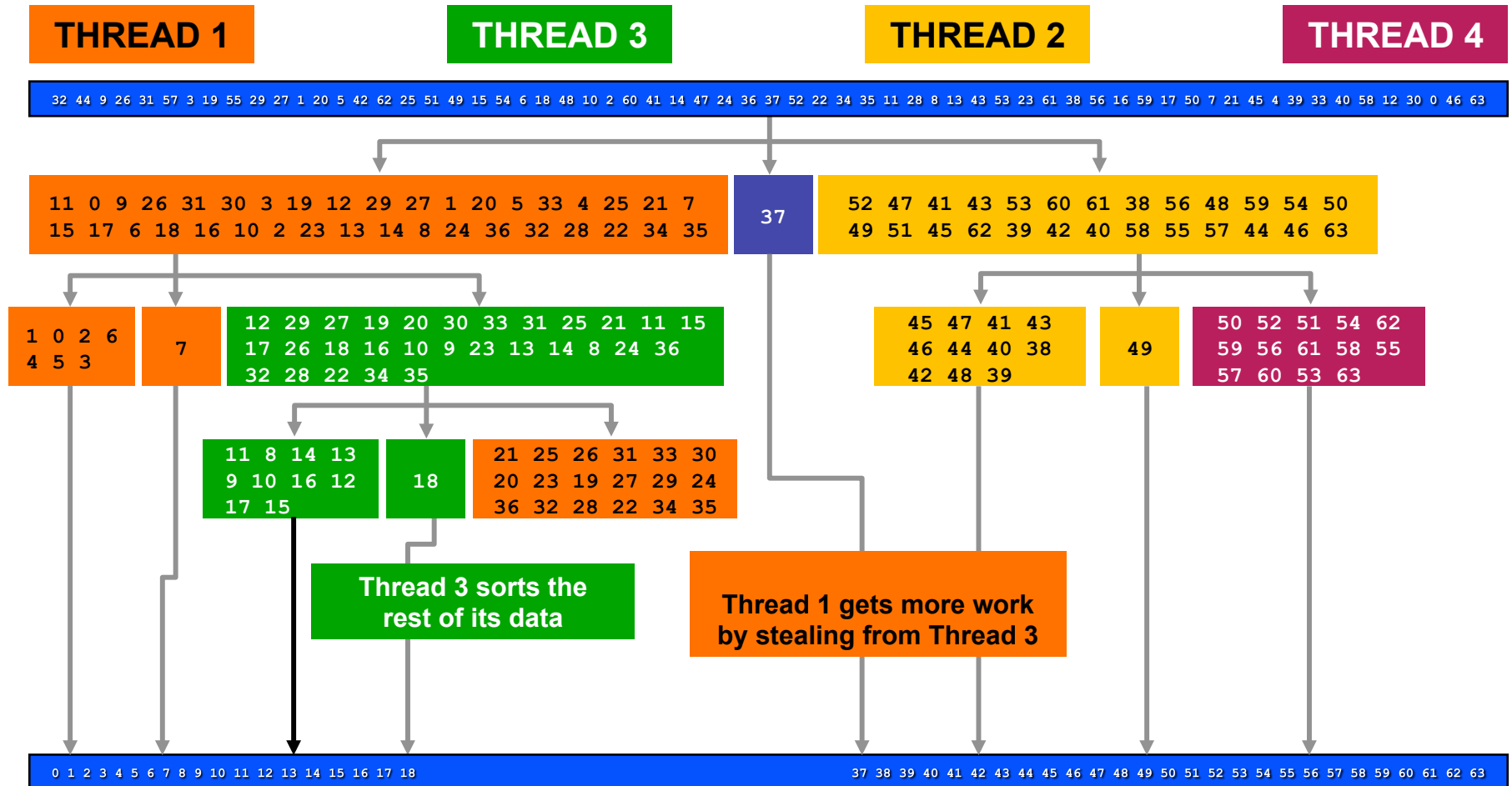
Quicksort – Step 3



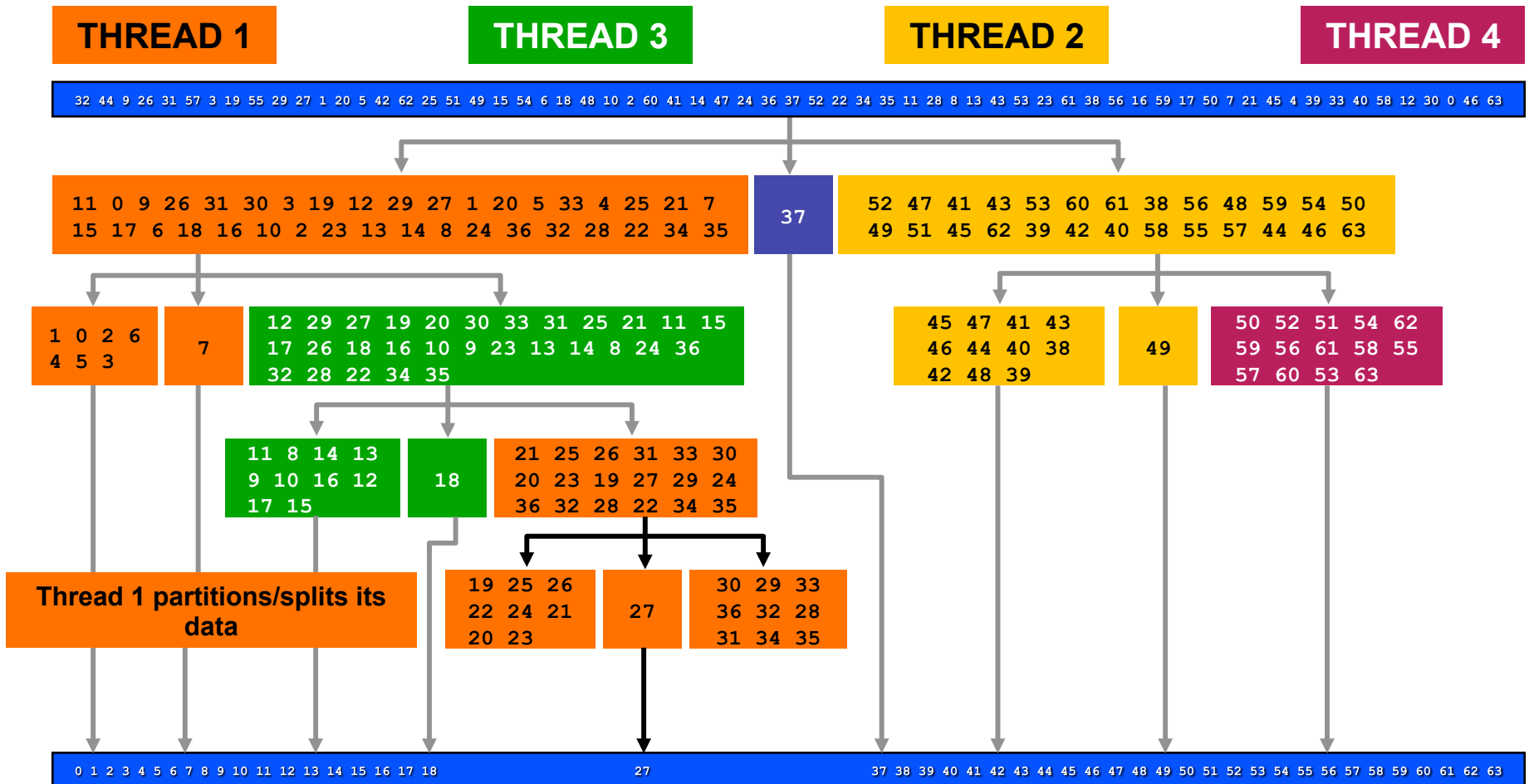
Quicksort – Step 4



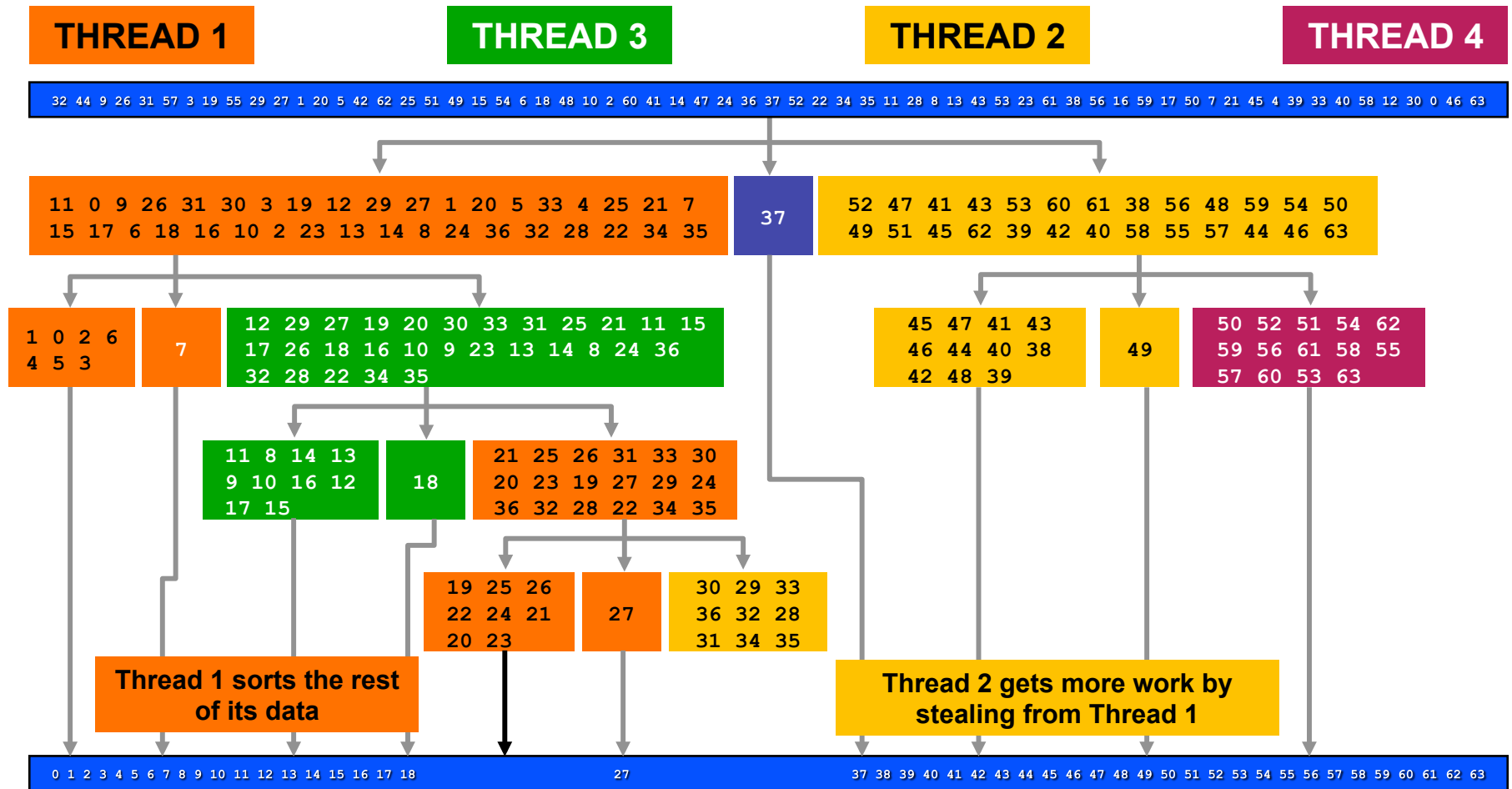
Quicksort – Step 5



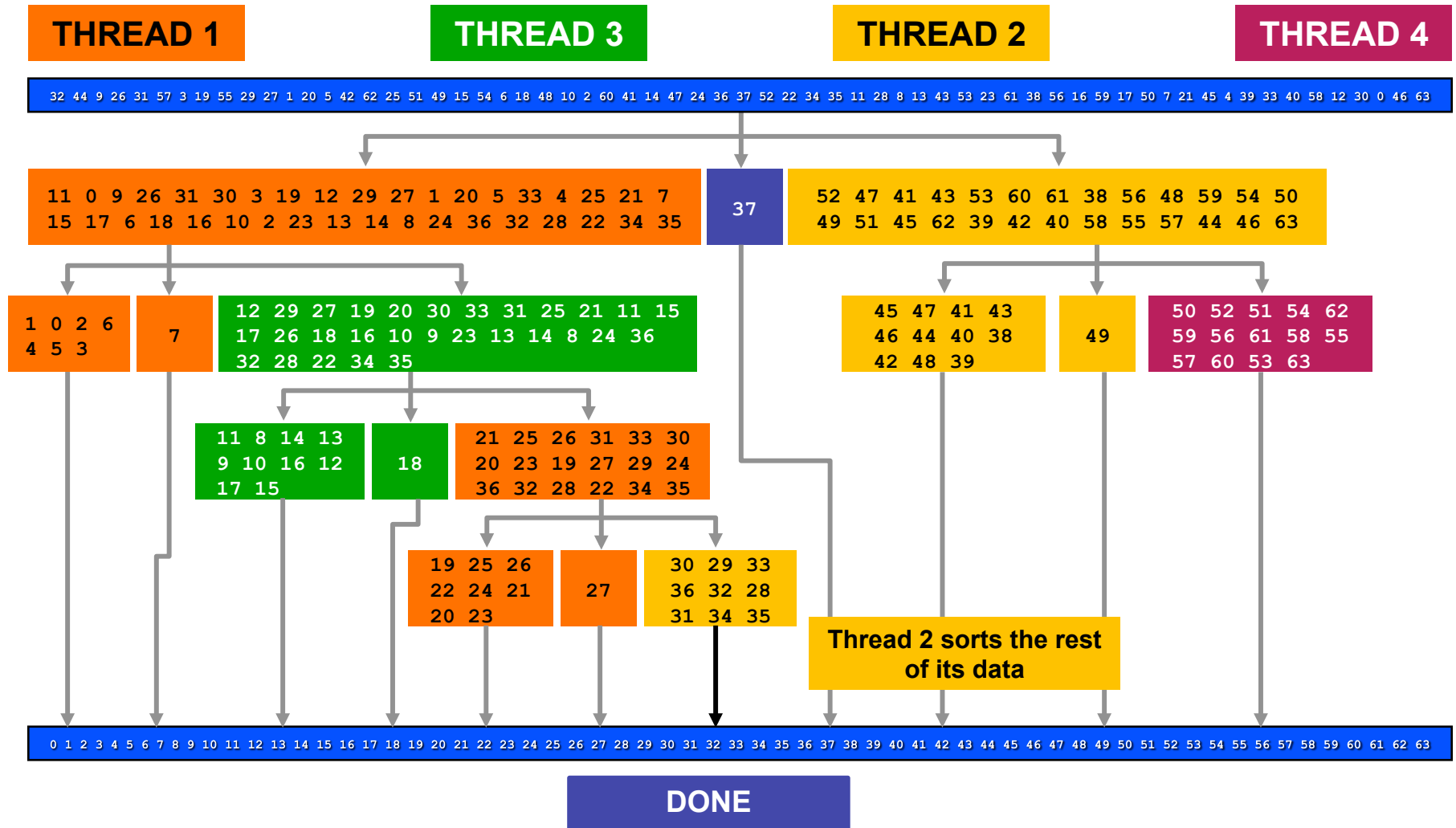
Quicksort – Step 6



Quicksort – Step 6



Quicksort – Step 7



An Example using parallel_for (1 of 3)

- ❖ Independent iterations and fixed/known bounds

```
const int N = 100000;

void change_array(float array, int M) {
    for (int i = 0; i < M; i++){
        array[i] *= 2;
    }
}

int main (){
    float A[N];
    initialize_array(A);
    change_array(A, N);
    return 0;
}
```

An Example using parallel_for (2 of 3)

- ❖ Include and initialize the library

```
#include <tbb/task_scheduler_init.h>
#include <tbb/parallel_blocked_range.h>
#include <tbb/parallel_for.h>
    change_array(A, N);
using namespace tbb;
}
int main () {
    task_scheduler_init init;
    float A[N];
    initialize_array(A);
    parallel_change_array(A, N);
    return 0;
}
```

Include Library Headers

Use namespace

Initialize scheduler

blue = original code
green = provided by TBB
red = boilerplate for library

An Example using parallel_for (3 of 3)

- ❖ Use the `parallel_for` algorithm

blue = original code
green = provided by TBB
red = boilerplate for library

```
class ChangeArrayBody {  
void change_array(float *array, int M) {  
    float *array;  
    for (int i = 0; i < M; i++){  
public:    array[i] *= 2;  
        ChangeArrayBody (float *a): array(a) {}  
    }  
    void operator() ( const blocked_range <int>& r ) const{  
        for (int i = r.begin(); i != r.end(); i++ ){  
            array[i] *= 2;  
        }  
    }  
};  
  
void parallel_change_array(float *array, int M) {  
    parallel_for (blocked_range <int>(0, M),  
                ChangeArrayBody(array), auto_partitioner());  
}
```

Define Task

Use algorithm

Use auto_partitioner()

An Example using `parallel_for` (3b of 3)

- ❖ Use the `parallel_for` algorithm

blue = original code
green = provided by TBB
red = boilerplate for library

```
class ChangeArrayBody {
    float *array;
public:
    ChangeArrayBody (float *a): array(a) {}
    void operator() ( const blocked_range <int>& r ) const{
        for (int i = r.begin(); i != r.end(); i++){
            array[i] *= 2;
        }
    }
};

void parallel_change_array(float *array, int M) {
    parallel_for (blocked_range <int>(0, M),
                 ChangeArrayBody (array),
                 auto_partitioner());
}
```

An Example using `parallel_for` with C++0x lambda functions

blue = original code
green = provided by TBB
red = boilerplate for library

```
void parallel_change_array(float *array, int M) {  
    parallel_for (blocked_range <int>(0, M),  
                 [=] (const blocked_range <int>& r ) const{  
                     for (int i = r.begin(); i != r.end(); i++ ){  
                         array[i] *= 2;  
                     }  
                 }  
    auto_partitioner());  
}
```

Use lambda function to implement `MyBody::operator()` inside the call to `parallel_for()`.

```
void change_array(float *array, int M) {  
    for (int i = 0; i < M; i++){  
        array[i] *= 2;  
    }  
}
```

Closer resemblance to sequential code

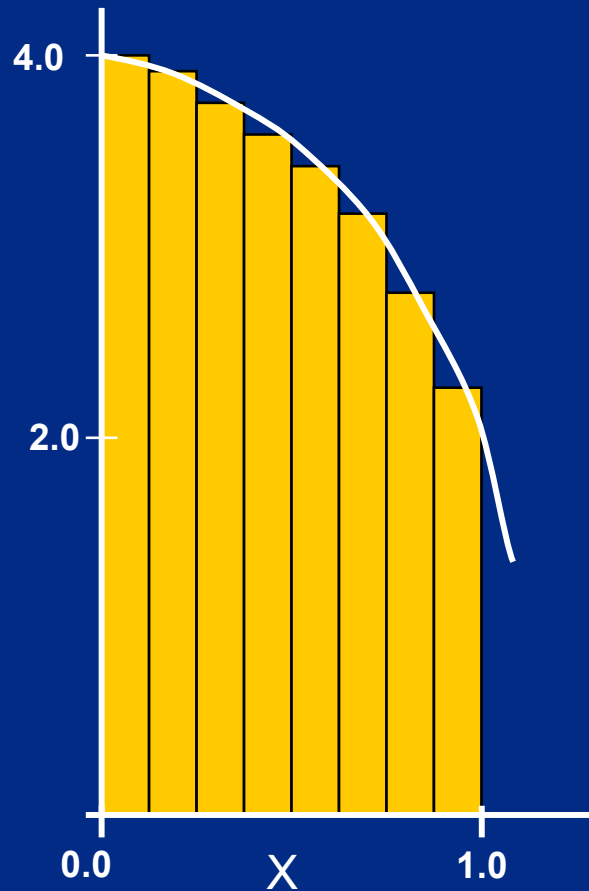
The parallel_reduce Template

```
template <typename Range, typename Body>  
void parallel_reduce (const Range& range, Body &body);
```

❖ Requirements for parallel_reduce Body

Body::Body(const Body&, <i>split</i>)	Splitting constructor
Body::~~Body()	Destructor
void Body::operator() (Range& <i>subrange</i>) const	Accumulate results from <i>subrange</i>
void Body::join(Body& <i>rhs</i>);	Merge result of <i>rhs</i> into the result of this.

Numerical Integration Example



```
static long num_steps=100000;
double step, pi;

void main(int argc, char*
argv[])
{ int i;
  double x, sum = 0.0;

  step = 1.0/(double) num_steps;
  for (i=0; i< num_steps; i++){
    x = (i+0.5)*step;
    sum += 4.0/(1.0 + x*x);
  }
  pi = step * sum;
  printf("Pi = %f\n",pi);
}
```

parallel_reduce Example

```
#include "tbb/parallel_reduce.h"
#include "tbb/task_scheduler_init.h"
#include "tbb/blocked_range.h"

using namespace tbb;

int main(int argc, char* argv[])
{
    double pi;
    double width = 1./((double)num_steps);
    MyPi step((double *const)&width);
    task_scheduler_init init;

    parallel_reduce(blocked_range<size_t>(0,num_steps), step,
                   auto_partitioner() );

    pi = step.sum*width;

    printf("The value of PI is %15.12f\n",pi);
    return 0;
}
```

blue = original code
green = provided by TBB
red = boilerplate for library

parallel_reduce Example

```
class MyPi {
  double *const my_step;
public:
  double sum;
  void operator()( const blocked_range<size_t>& r ) {
    double step = *my_step;
    double x;
    for (size_t i=r.begin(); i!=r.end(); ++i)
    {
      x = (i + .5)*step;
      sum += 4.0/(1.+ x*x);
    }
  }

  MyPi( MyPi& x, split ) : my_step(x.my_step), sum(0) {}

  void join( const MyPi& y ) {sum += y.sum;}

  MyPi(double *const step) : my_step(step), sum(0) {}
};
```

blue = original code
green = provided by TBB
red = boilerplate for library

accumulate results

join

Scalable Memory Allocators

- ❖ Serial memory allocation can easily become a bottleneck in multithreaded applications
 - Threads require mutual exclusion into shared heap
- ❖ False sharing - threads accessing the same cache line
 - Even accessing distinct locations, cache line can ping-pong
- ❖ Intel® Threading Building Blocks offers two choices for scalable memory allocation
 - Similar to the STL template class `std::allocator`
 - **`scalable_allocator`**
 - Offers scalability, but not protection from false sharing
 - Memory is returned to each thread from a separate pool
 - **`cache_aligned_allocator`**
 - Offers both scalability and false sharing protection

Concurrent Containers

- ❖ TBB Library provides highly concurrent containers
 - STL containers are not concurrency-friendly: attempt to modify them concurrently can corrupt container
 - Standard practice is to wrap a lock around STL containers
 - Turns container into serial bottleneck
- ❖ Library provides fine-grained locking or lockless implementations
 - Worse single-thread performance, but better scalability.
 - Can be used with the library, OpenMP, or native threads.

Synchronization Primitives

- ❖ Parallel tasks must sometimes touch shared data
 - When data updates might overlap, use mutual exclusion to avoid race
- ❖ High-level generic abstraction for HW atomic operations
 - Atomically protect update of single variable
- ❖ Critical regions of code are protected by scoped locks
 - The range of the lock is determined by its lifetime (scope)
 - Leaving lock scope calls the destructor, making it exception safe
 - Minimizing lock lifetime avoids possible contention
 - Several mutex behaviors are available

Atomic Execution

❖ `atomic<T>`

- T should be integral type or pointer type
- Full type-safe support for 8, 16, 32, and 64-bit integers

Operations

<code>'= x' and 'x = '</code>	read/write value of x
<code>x.fetch_and_store (y)</code>	<code>z = x, x = y, return z</code>
<code>x.fetch_and_add (y)</code>	<code>z = x, x += y, return z</code>
<code>x.compare_and_swap (y,p)</code>	<code>z = x, if (x==p) x=y; return z</code>

```
atomic <int> i;  
.  
.  
int z = i.fetch_and_add(2);
```

Mutex Concepts

- ❖ Mutexes are C++ objects based on scoped locking pattern
- ❖ Combined with locks, provide mutual exclusion

<code>M()</code>	Construct unlocked mutex
<code>~M()</code>	Destroy unlocked mutex
<code>typename M::scoped_lock</code>	Corresponding <code>scoped_lock</code> type
<code>M::scoped_lock ()</code>	Construct lock w/out acquiring a mutex
<code>M::scoped_lock (M&)</code>	Construct lock and acquire lock on mutex
<code>M::~~scoped_lock ()</code>	Release lock if acquired
<code>M::scoped_lock::acquire (M&)</code>	Acquire lock on mutex
<code>M::scoped_lock::release ()</code>	Release lock

Mutex Flavors

- ❖ `spin_mutex`
 - Non-reentrant, unfair, spins in the user space
 - VERY FAST in lightly contended situations; use if you need to protect very few instructions
- ❖ `queuing_mutex`
 - Non-reentrant, fair, spins in the user space
 - Use `Queuing_Mutex` when scalability and fairness are important
- ❖ `queuing_rw_mutex`
 - Non-reentrant, fair, spins in the user space
- ❖ `spin_rw_mutex`
 - Non-reentrant, fair, spins in the user space
 - Use `ReaderWriterMutex` to allow non-blocking read for multiple threads

spin_mutex Example

```
#include "tbb/spin_mutex.h"
Node* FreeList;
typedef spin_mutex FreeListMutexType;
FreelistMutexType FreelistMutex;

Node* AllocateNode () {
    Node* n;
    {
        FreelistMutexType::scoped_lock mylock(FreeListMutex);
        n = FreeList;
        if ( n ) FreeList = n->next;
    }
    if ( !n ) n = new Node();
    return n;
}

void FreeNode( Node* n ) {
    FreelistMutexType::scoped_lock mylock(FreeListMutex);
    n->next = FreeList;
    FreeList = n;
}
```

blue = original code
green = provided by TBB
red = boilerplate for library

One last question...

How do I know how many threads are available?

- ❖ Do not ask!
 - Not even the scheduler knows how many threads really are available
 - There may be other processes running on the machine
 - Routine may be nested inside other parallel routines
- ❖ Focus on dividing your program into tasks of sufficient size
 - Task should be big enough to amortize scheduler overhead
 - Choose decompositions with good depth-first cache locality and potential breadth-first parallelism
- ❖ Let the scheduler do the mapping



Lithe: Enabling Efficient Composition of Parallel Libraries

Heidi Pan, Benjamin Hindman, Krste Asanović

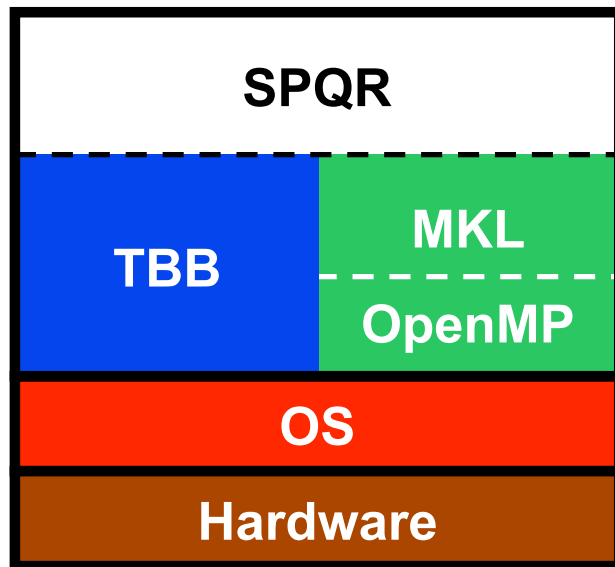
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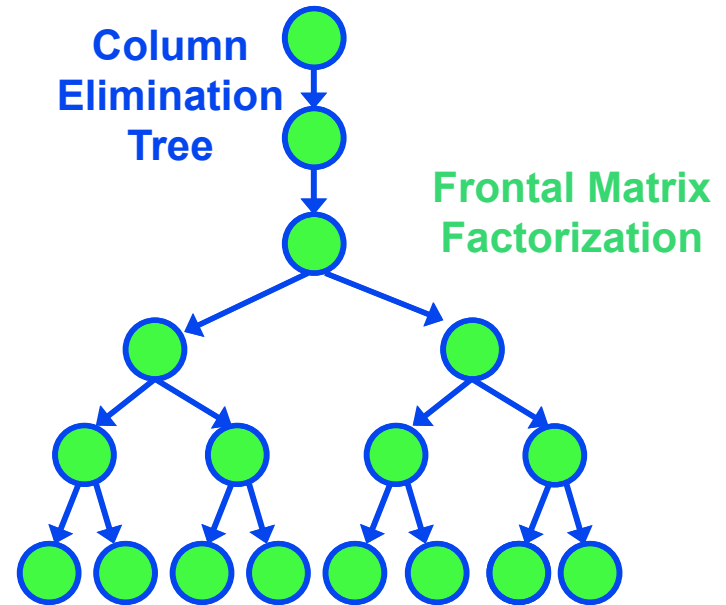
Real-World Parallel Composition Example

Sparse QR Factorization

(Tim Davis, Univ of Florida)



System Stack

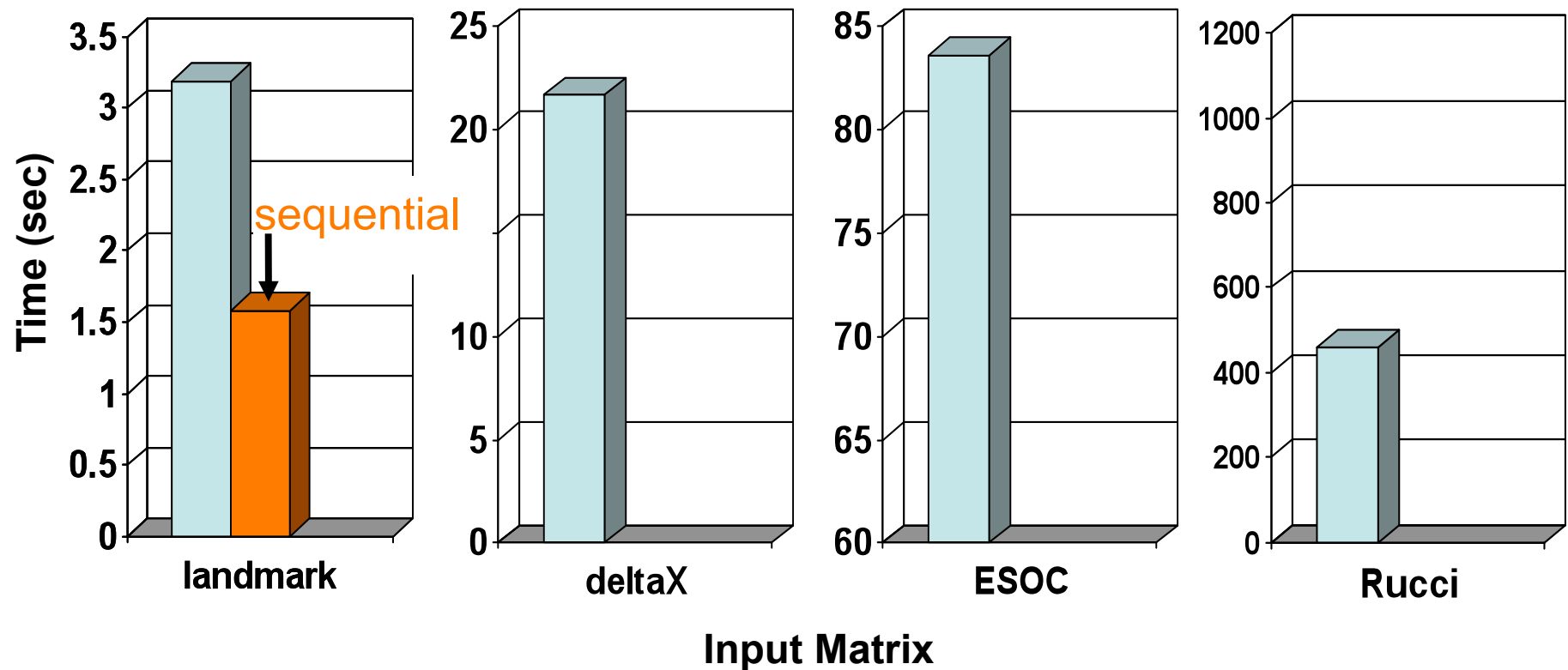


Software Architecture

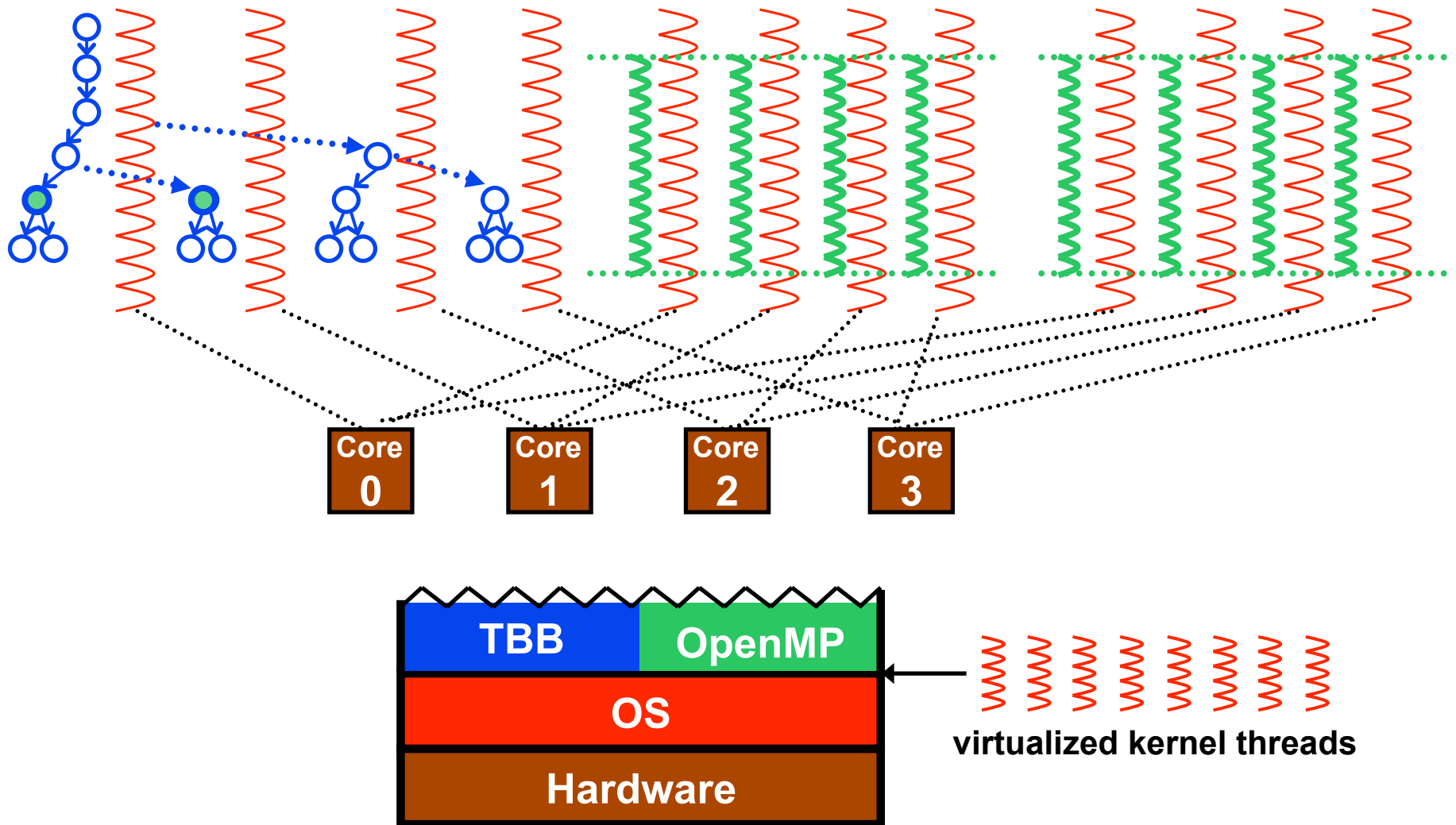
Out-of-the-Box Performance

Performance of SPQR on 16-core Machine

Out-of-the-Box



Out-of-the-Box Libraries Oversubscribe the Resources



MKL Quick Fix

Using Intel MKL with Threaded Applications

<http://www.intel.com/support/performance/tools/libraries/mkl/sb/CS-017177.htm>

Software Products

Intel® Math Kernel Library (Intel® MKL)
Using Intel® MKL with Threaded Applications

Page Contents:

- Memory Allocation MKL: Memory appears to be allocated and not released when calling some Intel MKL routines (e.g. sgtrf).
- Using Threading with BLAS and LAPACK
- Setting the Number of Threads
- Changing the Number of Threads
- Can I use Intel MKL if I thread my application?

Memory Allocation MKL
When calling some Intel® MKL routines, memory appears to be allocated and not released. One of the advantages of using OpenMP® is that it requires only one thread to be active even for single-processor systems. However, the first time the allocation persists until the application will allocate a stack equal to the amount of memory that is automatically allocated and the number of

Using Threading with BLAS
Intel MKL is threaded in a number of Level 3 BLAS, LAPACK, and FFT routines. We list them here with recommendations for situations in which conflicts exist. If the problem exists is appropriate.

If the user threads the program using OpenMP directives and uses the Intel® Compilers to compile the program, Intel MKL and the user program will both use the same threading library. Intel MKL tries to determine if it is in a parallel region in the program, and if it is, it does not spread its operations over multiple threads. But Intel MKL can be aware that it is in a parallel region only if the threaded program and Intel MKL are using the same threading library. If the user program is threaded by some other means, Intel MKL may operate in multithreaded mode and the computations may be corrupted. Here are several cases and our recommendations:

- User threads the program using OS threads (pthreads on Linux®, Win32® threads on Windows®). If more than one thread calls Intel MKL and the function being called is threaded, it is important that threading in Intel MKL be turned off. Set `OMP_NUM_THREADS=1` in the environment.
- User threads the program using OpenMP directives and/or pragmas and compiles the program using a compiler other than a compiler from Intel. This is more problematic because setting `OMP_NUM_THREADS` in the environment affects both the compiler's threading library and the threading

library with Intel MKL. In this case, the safe approach is to set `OMP_NUM_THREADS=1`.

- Multiple programs are running on a multiple-CPU system. In cluster applications, the parallel program can run separate instances of the program on each processor. However, the threading software will see multiple processors on the system even though each processor has a separate process running on it. In this case `OMP_NUM_THREADS` should be set to 1.
- If the variable `OMP_NUM_THREADS` environment variable is not set, then the default number of threads will be assumed 1.

Setting the Number of Threads for OpenMP® (OMP)

```
void main(int argc, char *argv){  
    double *a, *b, *c;  
    a = new double [SIZE*SIZE];  
    b = new double [SIZE*SIZE];  
    c = new double [SIZE*SIZE];  
  
    double alpha=1, beta=1;  
    int m=SIZE, n=SIZE, k=SIZE, lda=SIZE, ldb=SIZE, ldc=SIZE, i=0, j=0;  
    char transa='n', transb='n';  
  
    for (i=0; i<SIZE; i++){  
        for (j=0; j<SIZE; j++){  
            a[i*SIZE+j]= (double)(i+j);  
            b[i*SIZE+j]= (double)(i*j);  
            c[i*SIZE+j]= (double)0;  
        }  
    }  
    cblas_dgemm(CblasRowMajor, CblasNoTrans, CblasNoTrans,  
               m, n, k, alpha, a, lda, b, ldb, beta, c, ldc);  
}
```

```
printf("row\ta\tcol\n");  
for ( i=0;i<10;i++){  
    printf("%d:\t%f\t%f\n", i, a[i*SIZE], c[i*SIZE]);  
}  
  
omp_set_num_threads(1);  
  
for (i=0; i<SIZE; i++){  
    for (j=0; j<SIZE; j++){  
        a[i*SIZE+j]= (double)(i+j);  
        b[i*SIZE+j]= (double)(i*j);  
        c[i*SIZE+j]= (double)0;  
    }  
}
```

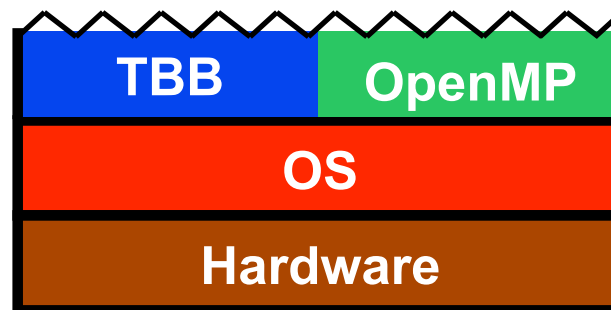
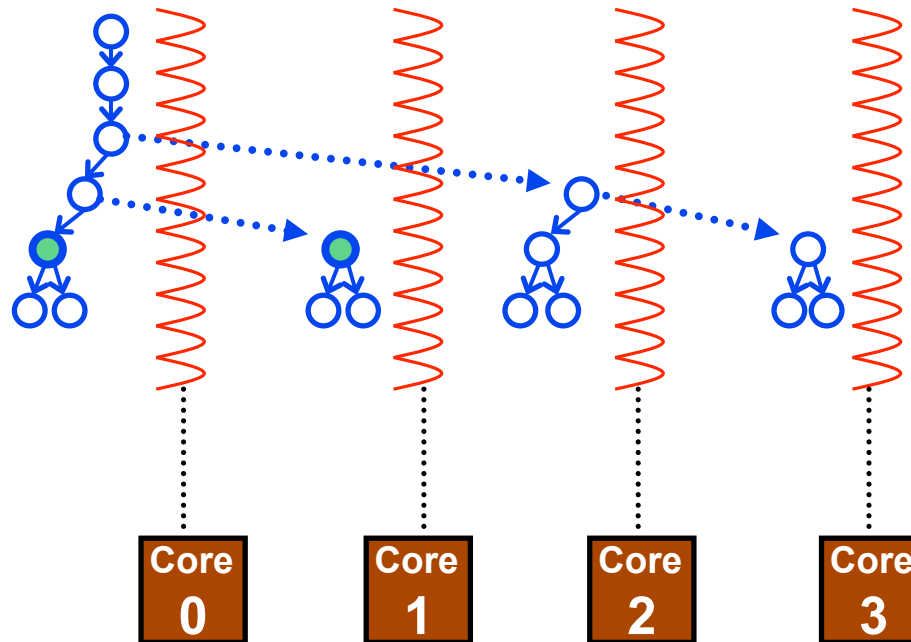
```
printf("row\ta\tcol\n");  
for ( i=0;i<10;i++){  
    printf("%d:\t%f\t%f\n", i, a[i*SIZE],  
c[i*SIZE]);  
}  
  
delete [] a;  
delete [] b;  
delete [] c;  
}
```

Can I use Intel MKL if I thread my application?

The Intel Math Kernel Library is designed and compiled for thread safety so it can be called from programs that are threaded. Calling Intel MKL routines that are threaded from multiple application threads can lead to conflict (including incorrect answers or program failures), if the calling library differs from the Intel MKL threading library.

• If more than one thread calls Intel MKL and the function being called is threaded, it is important that threading in Intel MKL be turned off. Set **OMP_NUM_THREADS=1** in the environment.

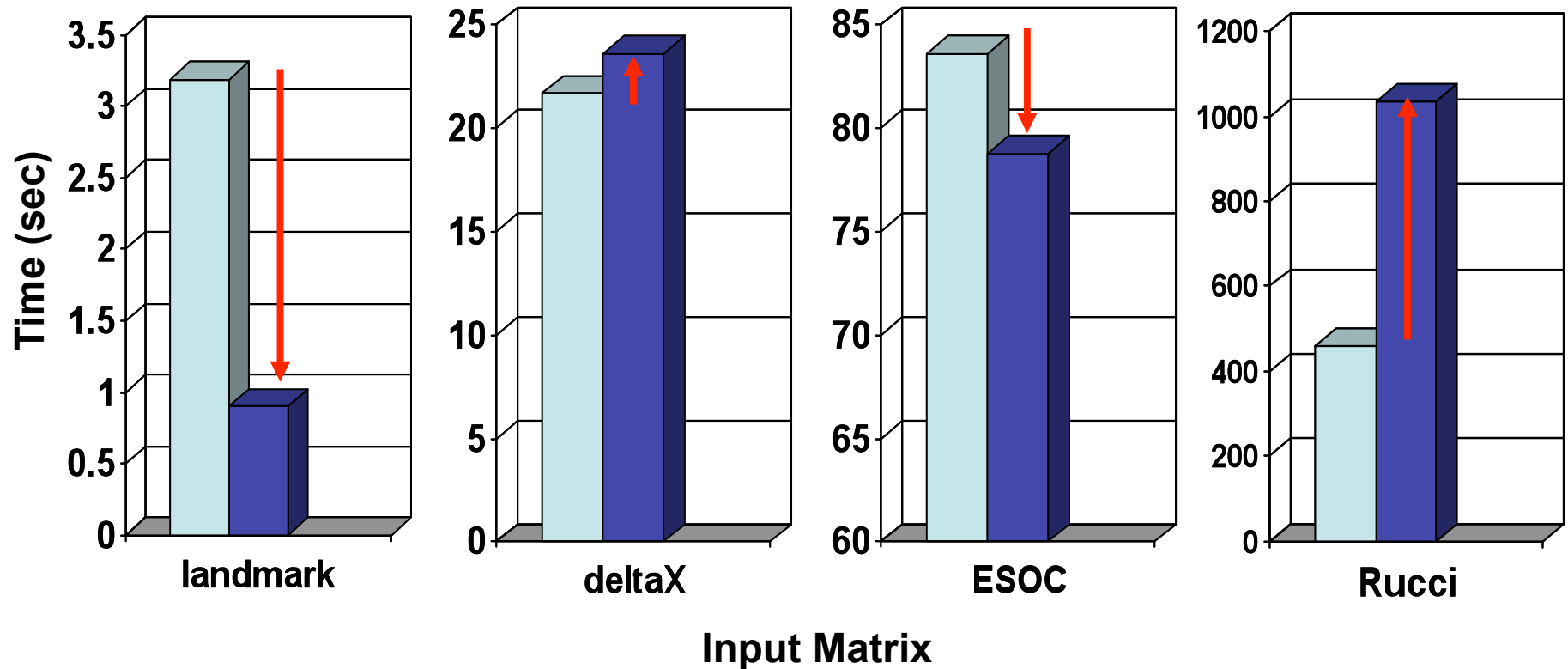
Sequential MKL in SPQR



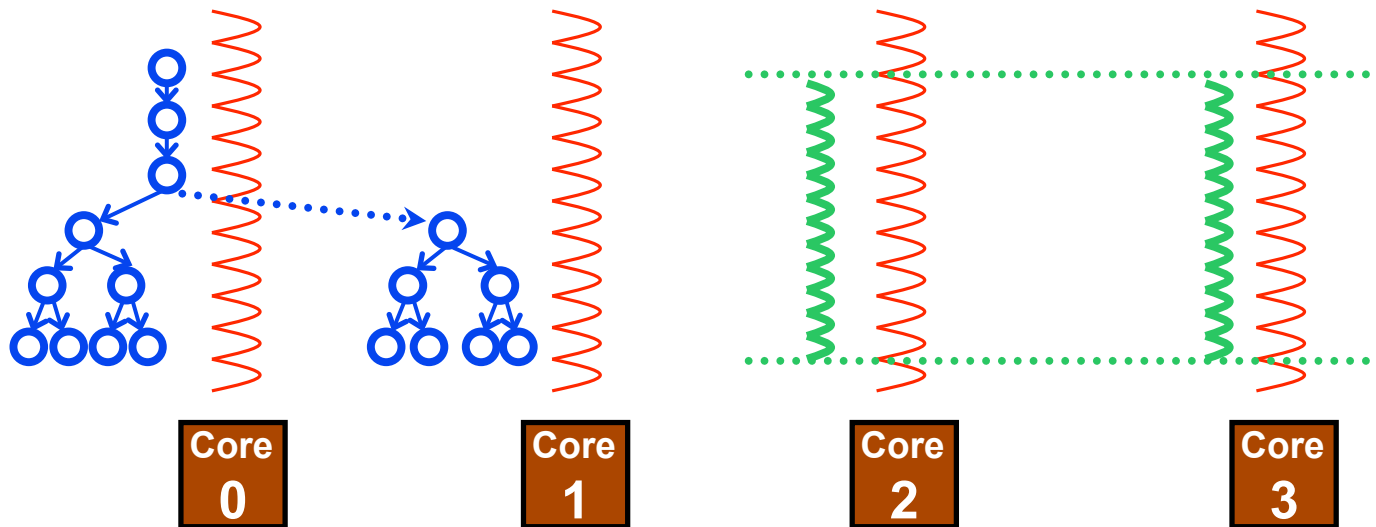
Sequential MKL Performance

Performance of SPQR on 16-core Machine

Out-of-the-Box Sequential MKL

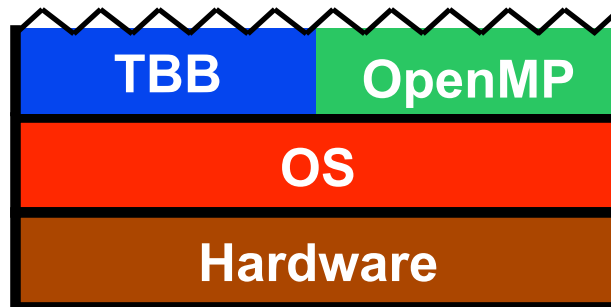


Share Resources Cooperatively



`TBB_NUM_THREADS = 2`

`OMP_NUM_THREADS = 2`

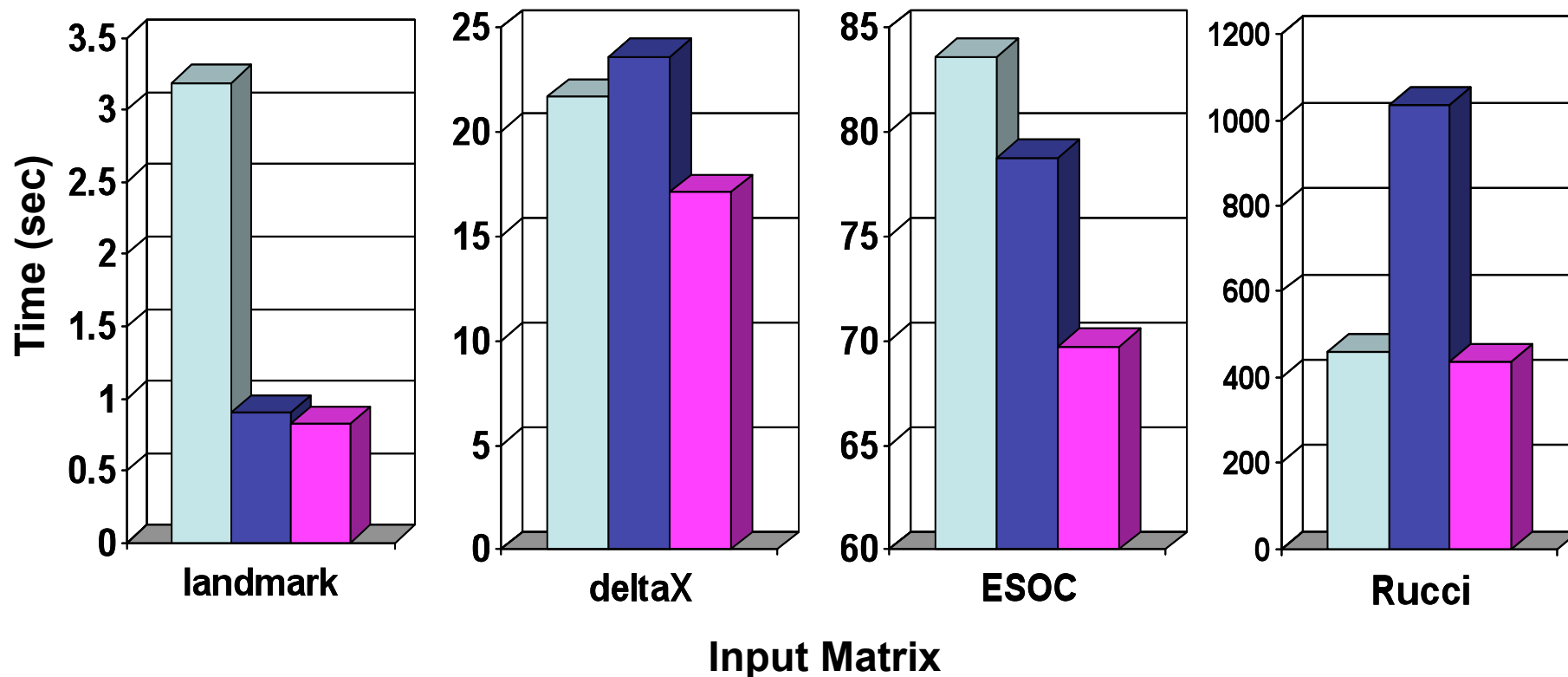


Tim Davis manually tunes libraries to effectively partition the resources.

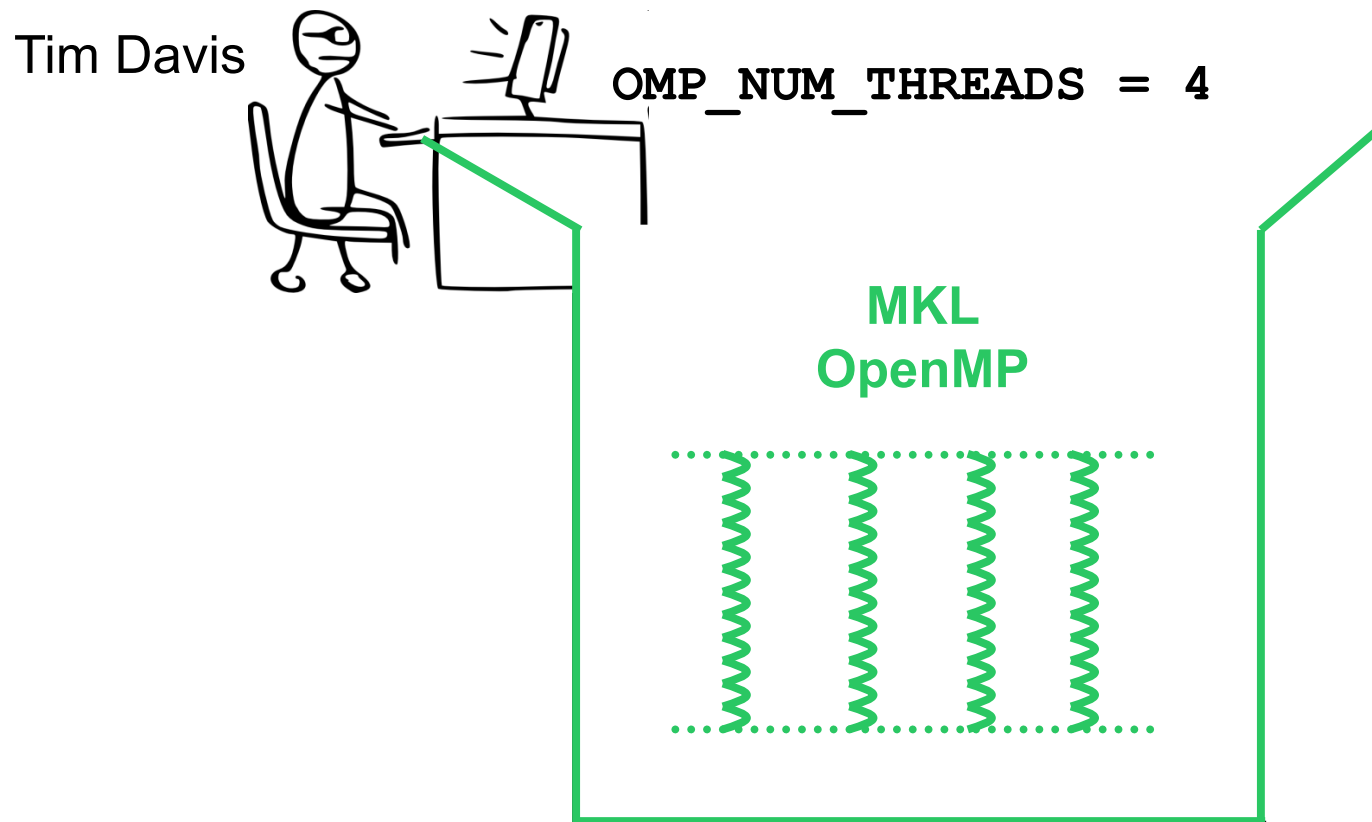
Manually Tuned Performance

Performance of SPQR on 16-core Machine

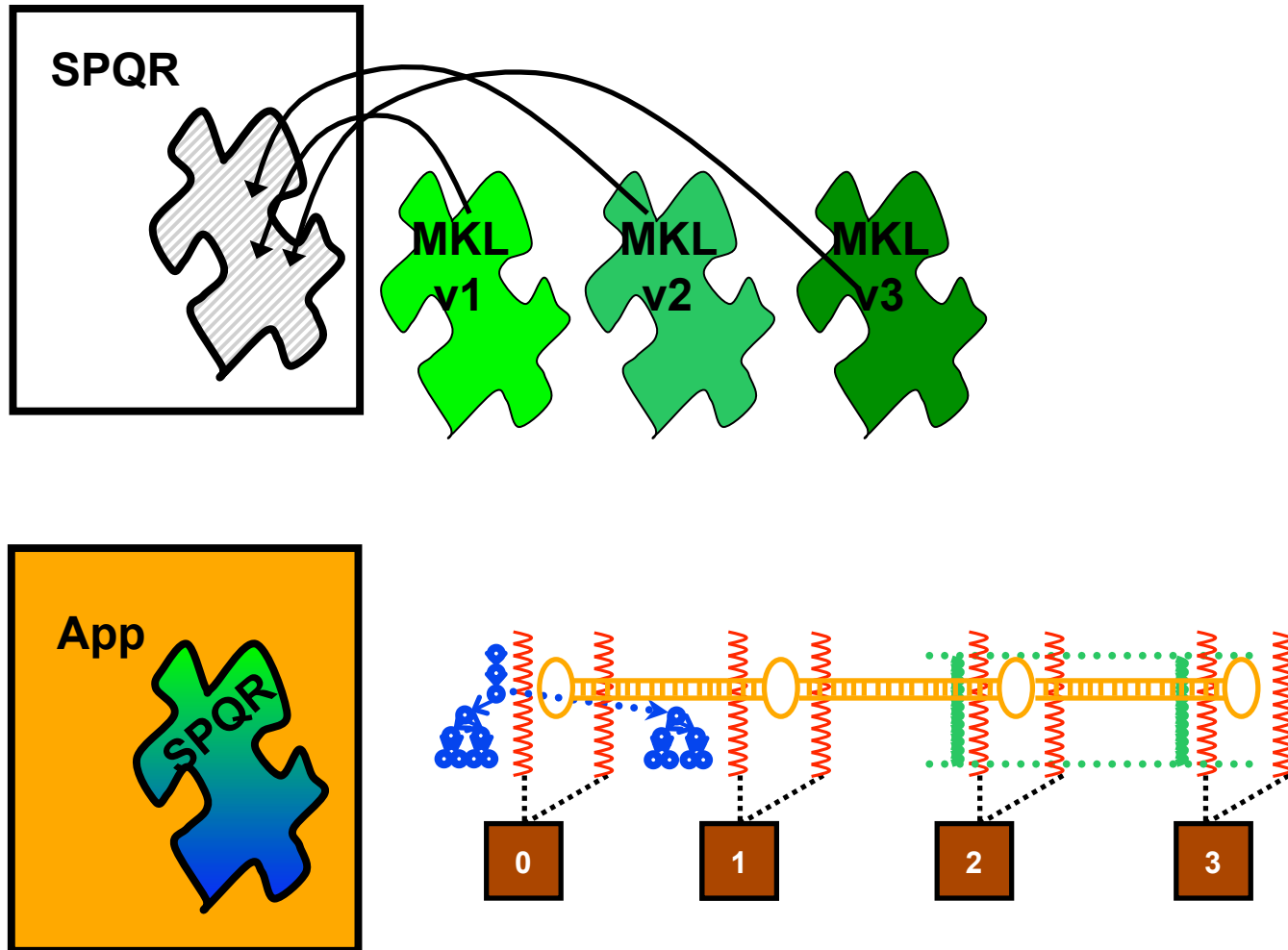
Out-of-the-Box Sequential MKL Manually Tuned



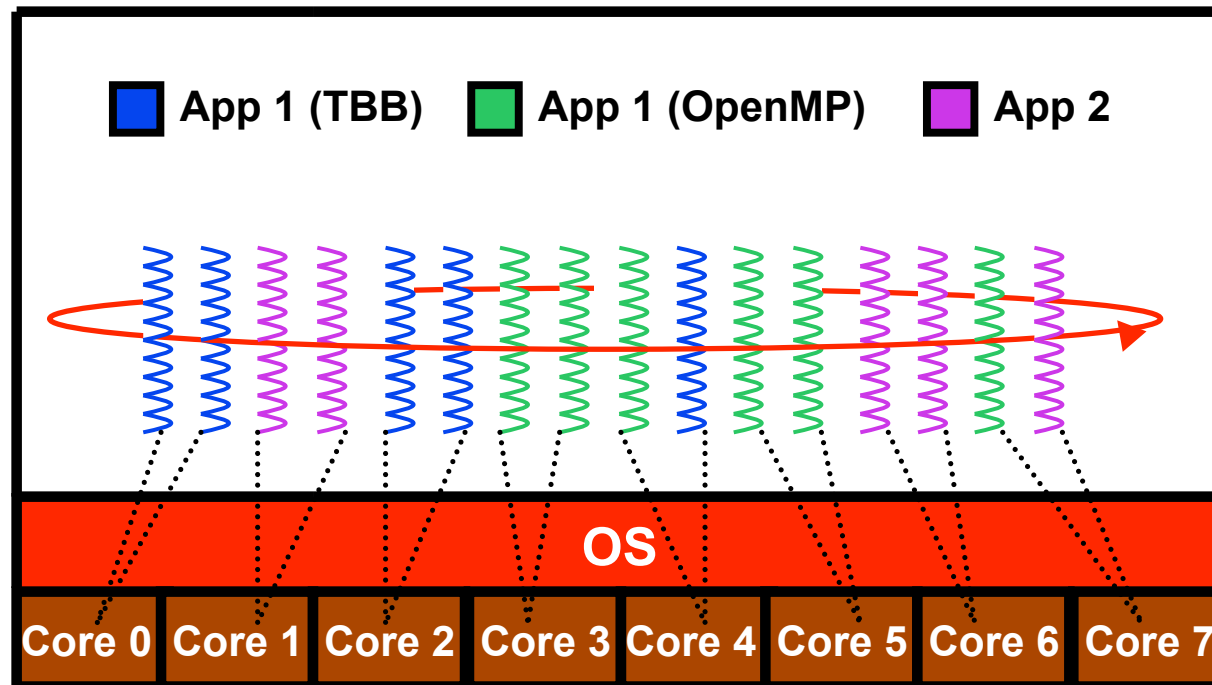
Manual Tuning Destroys Black Box Abstractions



Manual Tuning Destroys Code Reuse and Modular Updates

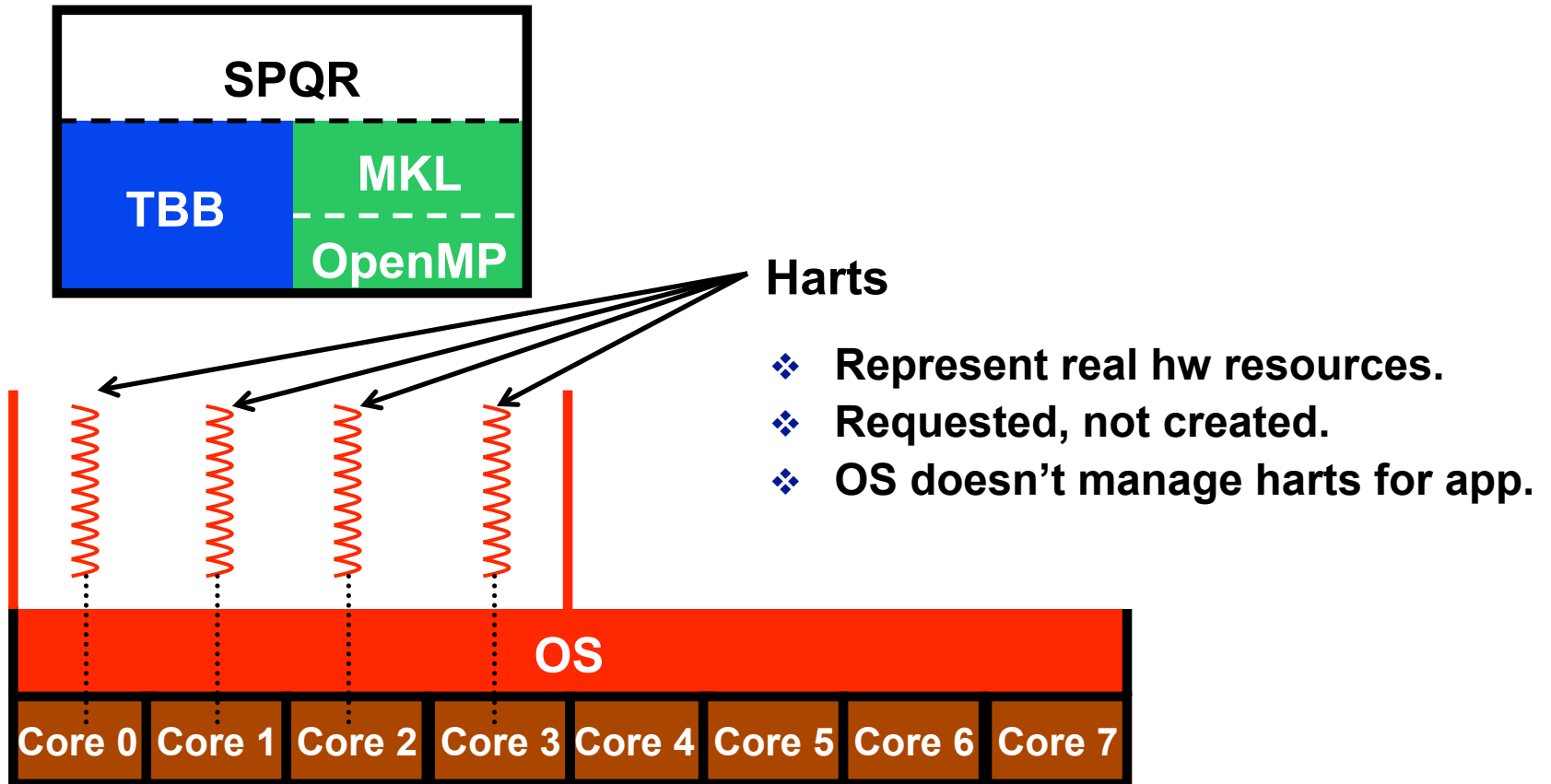


Virtualized Threads are Bad

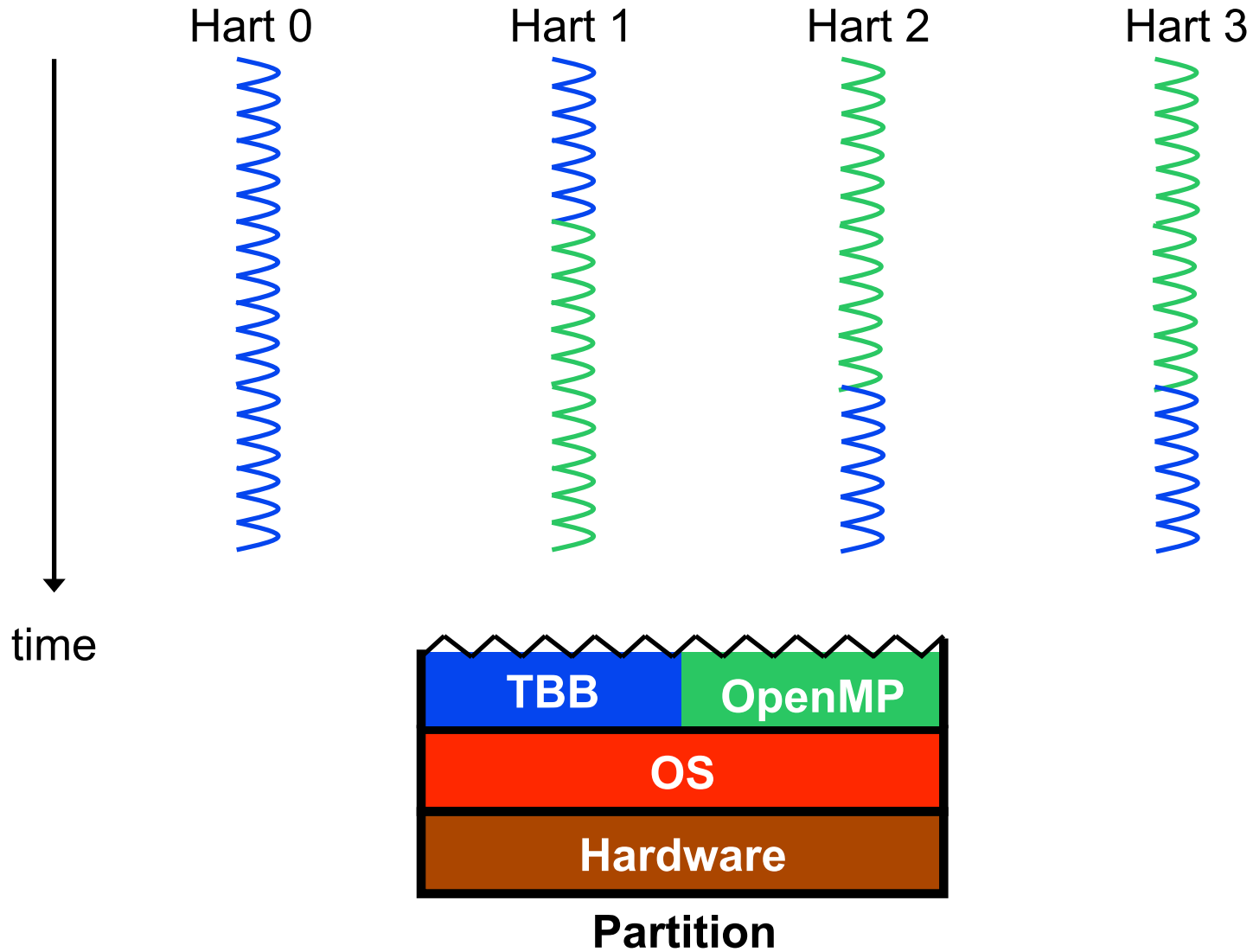


Different codes compete unproductively for resources.

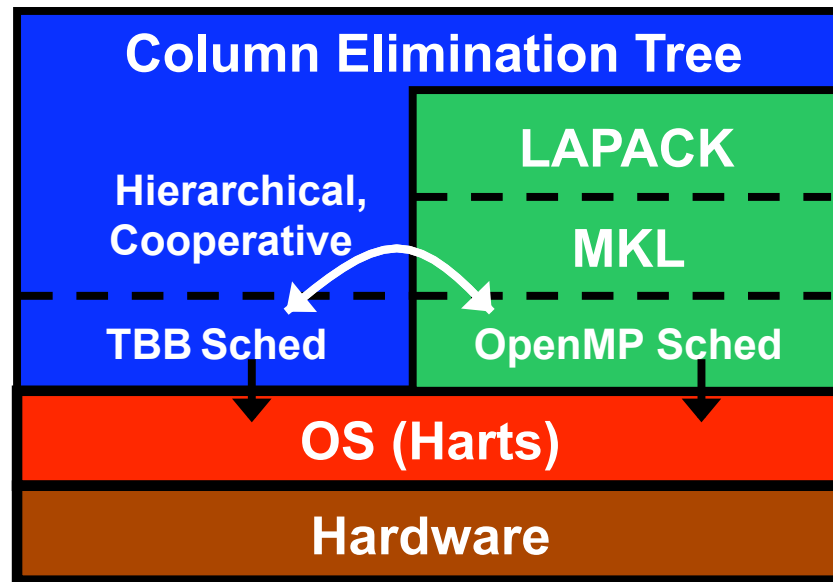
Harts: Hardware Thread Contexts



Sharing Harts

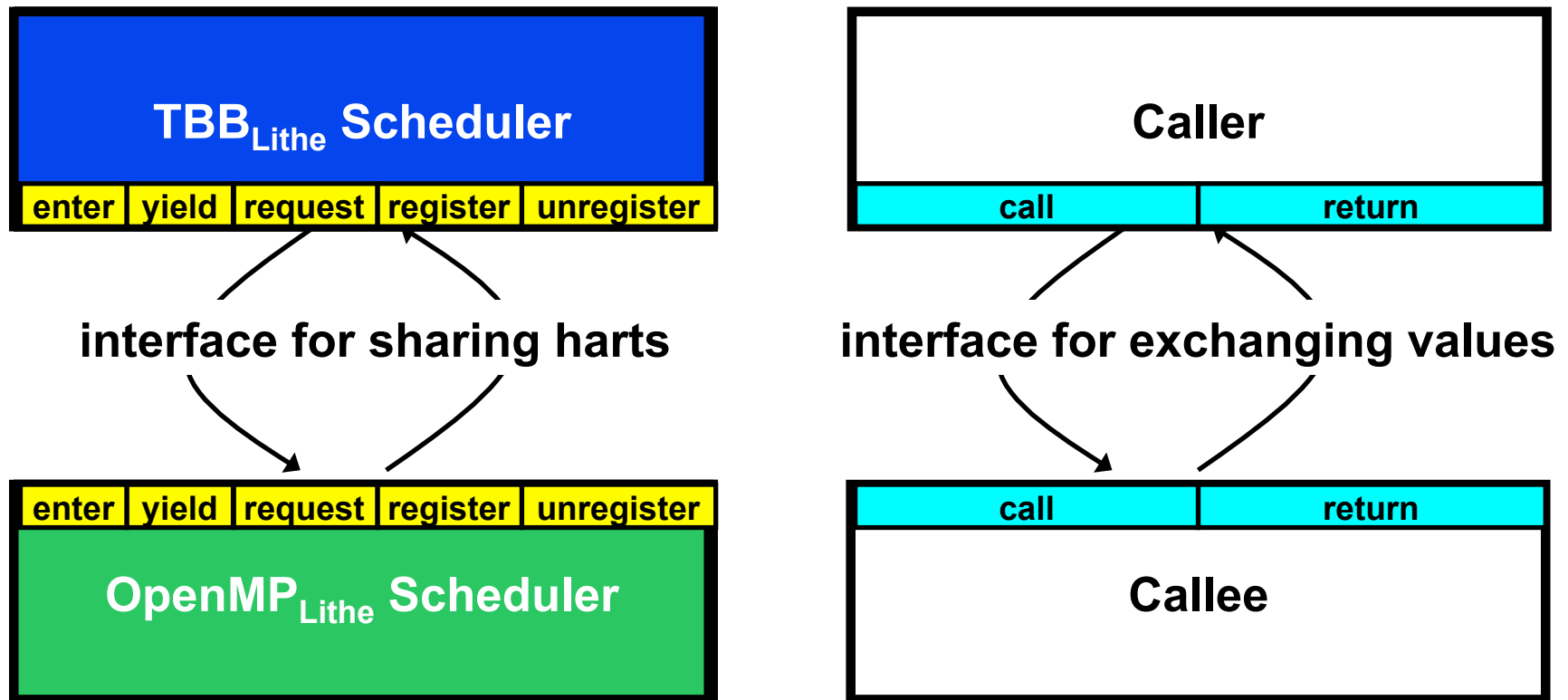


Hierarchical Cooperative Scheduling



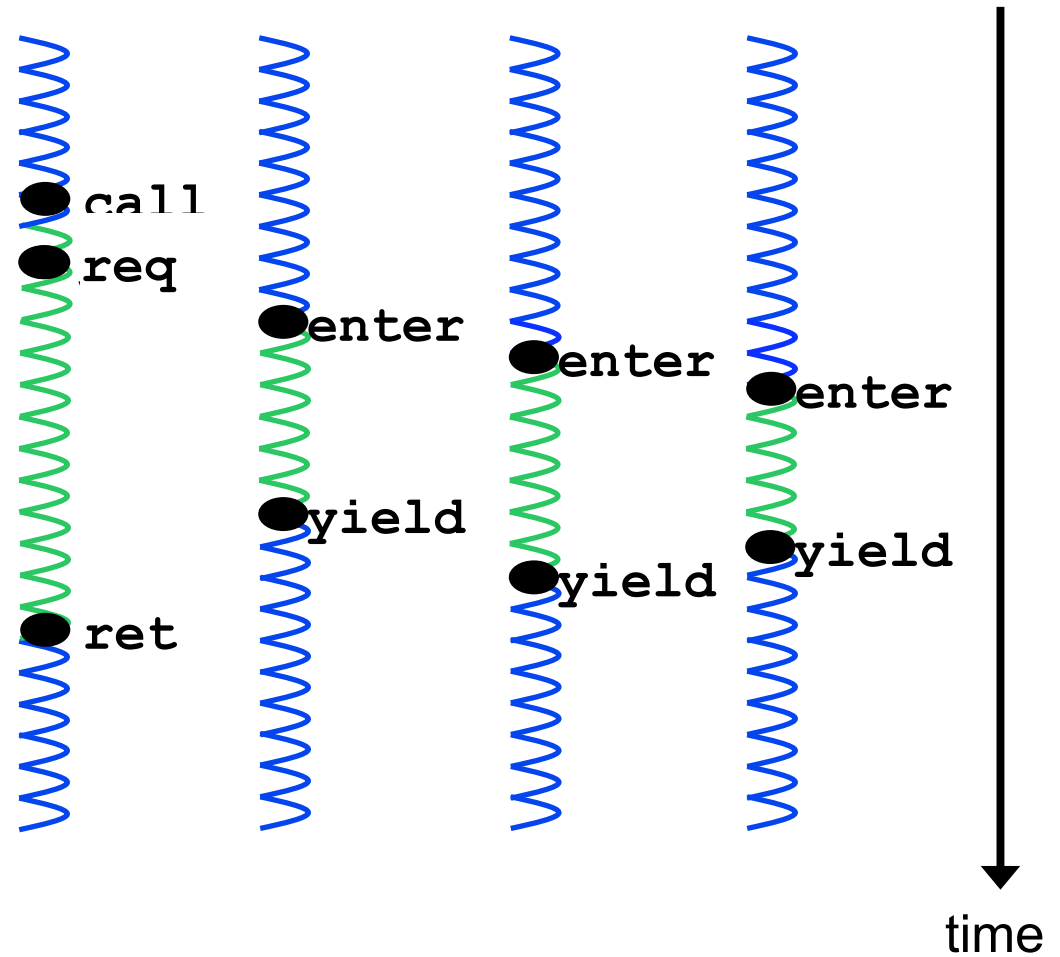
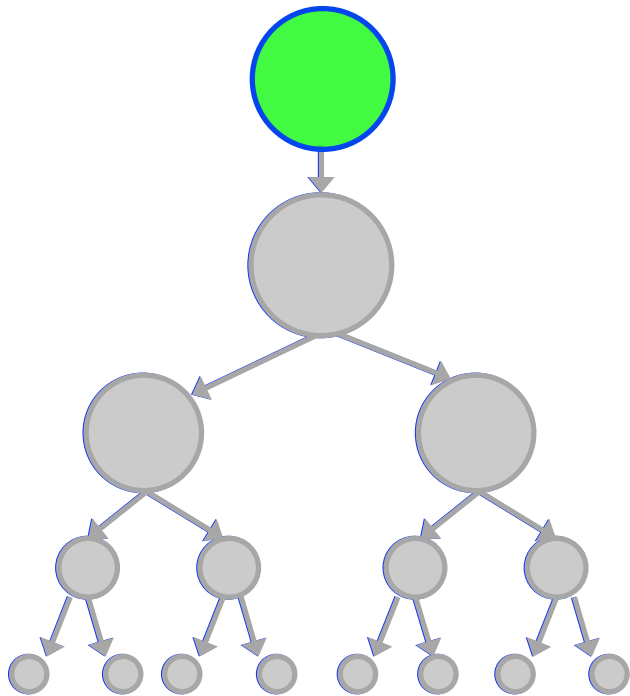
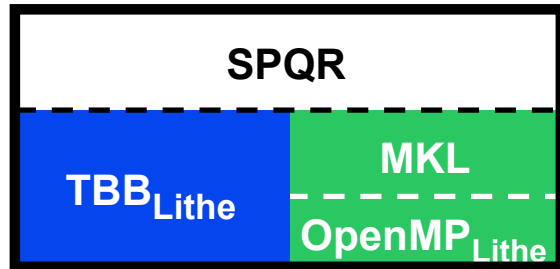
**Direct Control
of Resources**

Standard Lithe ABI

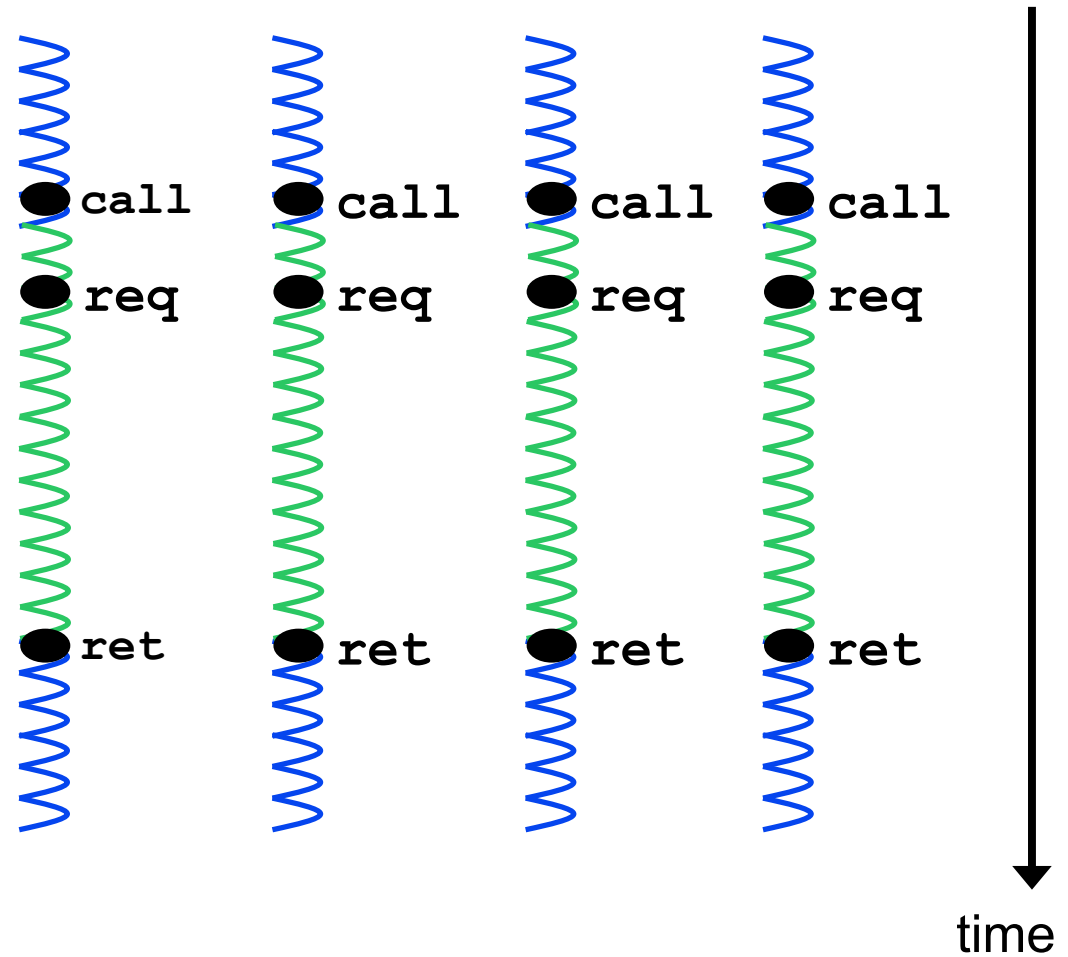
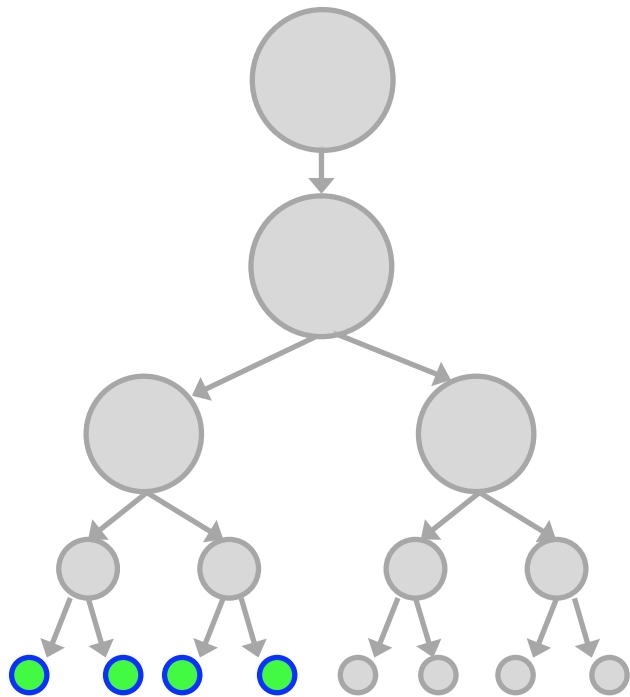
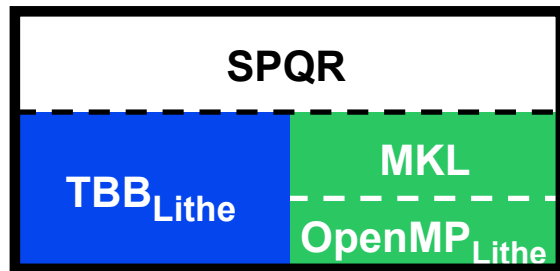


- ❖ Analogous to function call ABI for enabling interoperable codes.
- ❖ Mechanism for sharing harts, *not* policy.

SPQR with Lithe

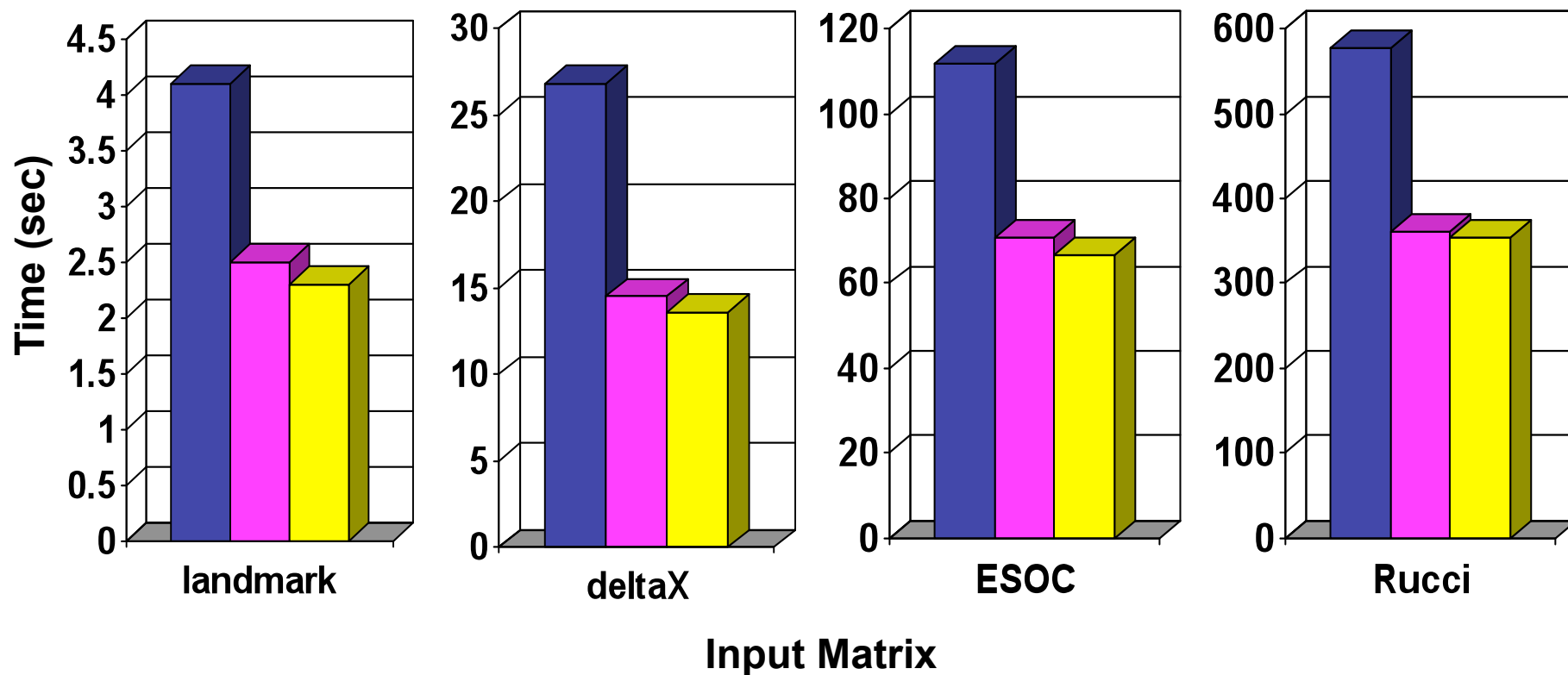


SPQR with Lithe

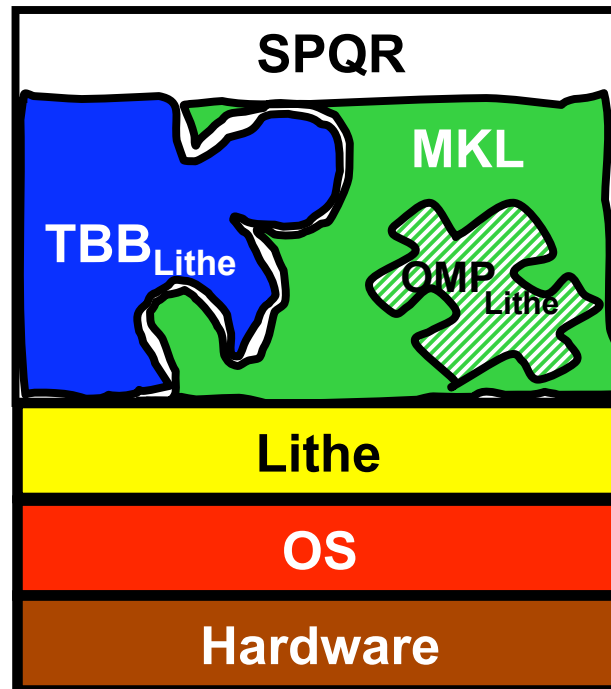


Performance of SPQR with Lithe

■ Out-of-the-Box ■ Manually Tuned ■ Lithe



Questions?



Lithe: Enabling Efficient Composition of Parallel Libraries

Acknowledgements

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